Configuring RCU In Your Linux Kernel

An Expert Embedded System Integrator's Guide
Brief Introduction to RCU
Brief Introduction to RCU: Example Application

- Schrödinger wants to construct an in-memory database for the animals in his zoo (example in July CACM article)
  - Births result in insertions, deaths in deletions
  - Queries from those interested in Schrödinger's animals
  - Lots of short-lived animals such as mice: High update rate
  - Great interest in Schrödinger's cat (perhaps queries from mice?)

- Simple approach: chained hash table with per-bucket locking
Perfect Partitioning, Thus Good Performance!
Read-Only Bucket-Locked Hash Table Performance

Why the dropoff???

2GHz Intel Xeon Westmere-EX, 1024 hash buckets
What If We Added More Hash Buckets?
Varying Number of Hash Buckets

2GHz Intel Xeon Westmere-EX

Still a dropoff...

Number of CPUs/Threads

Lookups per Millisecond
But What About NUMA Effects???
Check System's NUMA Layout

- /sys/devices/system/cpu/cpu0/cache/index0/shared_cpu_list: 0,32
- /sys/devices/system/cpu/cpu0/cache/index1/shared_cpu_list: 0,32
- /sys/devices/system/cpu/cpu0/cache/index2/shared_cpu_list: 0,32
- /sys/devices/system/cpu/cpu0/cache/index3/shared_cpu_list: 0-7,32-39

- Two hardware threads per core, eight cores per socket
- Try using only one CPU per socket: CPUs 0, 8, 16, and 24
Bucket-Locked Hash Performance: 1 CPU/Socket

This is not the sort of scalability that Schrödinger requires!!!
Why So Slow???
## Performance of Synchronization Mechanisms

### 16-CPU 2.8GHz Intel X5550 (Nehalem) System

<table>
<thead>
<tr>
<th>Operation</th>
<th>Cost (ns)</th>
<th>Ratio</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clock period</td>
<td>0.4</td>
<td>1</td>
</tr>
<tr>
<td>“Best-case” CAS</td>
<td>12.2</td>
<td>33.8</td>
</tr>
<tr>
<td>Best-case lock</td>
<td>25.6</td>
<td>71.2</td>
</tr>
<tr>
<td>Single cache miss</td>
<td>12.9</td>
<td>35.8</td>
</tr>
<tr>
<td>CAS cache miss</td>
<td>7.0</td>
<td>19.4</td>
</tr>
<tr>
<td>Single cache miss (off-core)</td>
<td>31.2</td>
<td>86.6</td>
</tr>
<tr>
<td>CAS cache miss (off-core)</td>
<td>31.2</td>
<td>86.5</td>
</tr>
<tr>
<td>Single cache miss (off-socket)</td>
<td>92.4</td>
<td>256.7</td>
</tr>
<tr>
<td>CAS cache miss (off-socket)</td>
<td>95.9</td>
<td>266.4</td>
</tr>
</tbody>
</table>

*Typical synchronization mechanisms do this a lot*

*Heavily optimized reader-writer lock might get here for readers (but too bad about those poor writers...)*

*Need to be here! (Partitioning/RCU)*
Just Don't Use Heavyweight Instructions!
Implementing Read-Copy Update (RCU)

- Lightest-weight conceivable read-side primitives
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  - /* Assume non-preemptible (run-to-block) environment. */
  - #define rcu_read_lock()
  - #define rcu_read_unlock()
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- How can something that does not affect machine state possibly be used as a synchronization primitive???
RCU: Publish New Data, Remove Old Data
Publication of And Subscription to New Data

Key:
- Dangerous for updates: all readers can access
- Still dangerous for updates: pre-existing readers can access (next slide)
- Safe for updates: inaccessible to all readers

But if all we do is add, we have a big memory leak!!!
RCU Removal From Linked List

- Combines waiting for readers and multiple versions:
  - Writer removes the cat's element from the list (list_del_rcu())
  - Writer waits for all readers to finish (synchronize_rcu())
  - Writer can then free the cat's element (kfree())
RCU Removal From Linked List

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But how can software deal with two different versions simultaneously???
Two Different Versions Simultaneously???

I think the poor thing has expired.  

No!

Where there is a brain-wave, there is a way!
RCU Removal From Linked List

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  - Writer removes the cat's element from the list (list_del_rcu())
  - Writer waits for all readers to finish (synchronize_rcu())
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But if readers leave no trace in memory, how can we possibly tell when they are done??
Waiting for Pre-Existing Readers: QSBR

- Non-preemptive environment (CONFIG_PREEMPT=n)
  - RCU readers are not permitted to block
  - Same rule as for tasks holding spinlocks

- CPU context switch means all that CPU's readers are done

- Grace period ends after all CPUs execute a context switch

![Diagram showing synchronization process](Image)
Synchronizing Without Machine-State Change

- But rcu_read_lock() does not need to change machine state
  - Instead, it acts on the developer, who must avoid blocking within RCU read-side critical sections
  - Or, more generally, avoid quiescent states within RCU read-side critical sections

- RCU is therefore synchronization via social engineering

- As do all other synchronization mechanisms:
  - “Avoid data races”
  - “Protect specified variables with the corresponding lock”
  - “Access shared variables only within transactions”
RCU Usage: Readers

- Pointer to RCU-protected object guaranteed to exist throughout RCU read-side critical section
  
  ```c
  rcu_read_lock(); /* Start critical section. */
  p = rcu_dereference(cptr);
  /* *p guaranteed to exist. */
  do_something_with(p);
  rcu_read_unlock(); /* End critical section. */
  /* *p might be freed!!! */
  ```

- The `rcu_read_lock()`, `rcu_dereference()` and `rcu_read_unlock()` primitives are very light weight

- However, updaters must take care...
RCU Usage: Updaters

- Updaters must wait for an *RCU grace period* to elapse between making something inaccessible to readers and freeing it
  
  ```c
  spin_lock(&updater_lock);
  q = cptr;
  rcu_assign_pointer(cptr, new_p);
  spin_unlock(&updater_lock);
  synchronize_rcu(); /* Wait for grace period. */
  kfree(q);
  ```

- RCU grace period waits for all pre-exiting readers to complete their RCU read-side critical sections
Schrödinger's Zoo: Read-Only

RCU and hazard pointers scale quite well!!!
Schrödinger's Zoo: Read-Only Cat-Heavy Workload

Per-bucket locking doesn't help if all accesses are to one bucket!
RCU Area of Applicability

- **Read-Mostly, Stale & Inconsistent Data OK** (RCU Works Great!!!)
- **Read-Mostly, Need Consistent Data** (RCU Works OK)
- **Read-Write, Need Consistent Data** (RCU Might Be OK...)
- **Update-Mostly, Need Consistent Data** (RCU is Really Unlikely to be the Right Tool For The Job, But It Can:
  1. Provide Existence Guarantees For Update-Friendly Mechanisms
  2. Provide Wait-Free Read-Side Primitives for Real-Time Use)

Schrodinger's zoo is in blue: Can't tell exactly when an animal is born or dies anyway! Plus, no lock you can hold will prevent an animal's death...
RCU Applicability to the Linux Kernel
Configuring RCU
Configuring RCU: Kconfig

- **PREEMPT=y** implies **TREE_PREEMPT_RCU=y**
  - Needed to avoid RCU readers degrading scheduling latency
  - TINY_PREEMPT_RCU is gone as of v3.11.

- **NO_HZ_FULL=y** implies **RCU_USER_QS**
  - More on this from Frederic Weisbecker

- **RCU_NOCB_CPU=y** and **RCU_NOCB_CPU_ALL=y** to offload callback invocation
  - Can pin resulting kthreads to “housekeeping” CPUs
  - But run at SCHED_OTHER, so less disruptive regardless of pinning
  - See next slide...
The Problem With Non-Offloaded RCU Callbacks

RCU callback runs in softirq context, likely disrupting whatever was supposed to execute at about this time...
Offload RCU Callbacks (Inspired by Houston/Korty)

CPU 1

rcuo kthread

Grace Period

call_rcu()

Callback Invoked

Scheduler controls placement (or can place manually)

No disruption!

CPU 2

rcuo kthread

Grace Period

call_rcu()

Callback Invoked

Runs in process context with bh disabled
Offloadable RCU Callbacks: Limitations and Futures

- Must reboot to reconfigure no-CBs CPUs
  - rcu_nocb_poll kernel command-line parameter gives list of no-CB CPUs
  - Races between reconfiguring, registering callbacks, rcu_barrier(), grace periods and who knows what all else are far from pretty! (But you can move the kthreads around w/out boot.)
  - Just offload all of them and don't worry about reconfiguring!!!

- No energy-efficiency code: lazy & non-lazy CBs? Non-lazy!
  - This can be fixed if it becomes a problem – but show me the problem first!

- No-CBs CPUs' kthreads not subject to priority boosting
  - Rely on configurations restrictions: priority boosting not heavily used anyway

- Setting all no-CBs CPUs' kthreads to RT prio w/out pinning them: bad!
  - So either leave them as SCHED_OTHER or pin them
  - Or run only on small systems where global scheduling works OK

- Thus, I do not expect no-CBs path to completely replace current CB path
  - At least not without a lot of experience and performance evaluation
  - Maybe in a few years if experience indicates that this simplification is safe for all workloads
Configuring RCU: Kconfig Debugging Options (1/3)

- **DEBUG_OBJECTS_RCU_HEAD**(=n): Check for duplicate call_rcu() invocations
- **PROVE_RCU**(=n): Check for accessing RCU-protected pointers outside of RCU read-side critical sections
- **SPARSE_RCU_POINTER**(=n): When building with sparse, check usage of RCU-protected pointers.
- **PROVE_RCU_REPEATEDLY**(=n): Don't stop checking after the first PROVE_RCU splat
- **PROVE_RCU_DELAY**(=n): Insert delays to provoke allegedly-fixed RCU bugs

Please use the options in **green** when adding new kernel code that uses RCU.
Configuring RCU: Kconfig Debugging Options (2/3)

- **RCU_TORTURE_TEST=n**: RCU torture tests, which may be built-in or built as module.
- **RCU_TORTURE_TEST_RUNNABLE=n**: If rcutorture is built in, start running at boot time.
- **RCU_CPU_STALL_TIMEOUT=21**: Number of seconds to wait before complaining about too-long RCU grace period.
- **RCU_CPU_STALL_VERBOSE=y**: Print per-task information for any tasks blocking a preemptible-RCU grace period.
- **RCU_CPU_STALL_INFO=n**: Print additional information for each CPU stalling the current grace period.
Real Time Linux Workshop, October 30, 2013

Configuring RCU: Kconfig Debugging Options (3/3)

- **TREE_RCU_TRACE=n** to enable full event tracing
  - Also enables debugfs tracing
  - Usually used for debugging RCU itself

- **RCU_BOOST=n** in case of accidental infinite loops
  - Prevents preempted readers from indefinitely blocking grace periods
  - But consider instead the approach on the next slide

- **RCU_BOOST_PRIO=1**: Set higher than infinite loop
  - Otherwise, infinite loop will continue to block grace period
  - Defaults of 1 only helps with SCHED_OTHER infinite loops

- **RCU_BOOST_DELAY=500**: Wait this long before boosting
  - Maximum delay is 3000 (3 seconds)
Alternative to CPU-Bound Execution

Use a pair of variables to mediate transitions:
1. am_awake: End of sleep
2. ready_sleep: Hand off to newly awakened thread.
Configuring RCU: Special-Purpose Kconfig Options

- **RCU_FAST_NO_HZ=y**: Reduce scheduling-clock interrupts while idle CPU has RCU callbacks. Increases from-idle scheduling latency, improves battery lifetime.

- **RCU_FANOUT**: Control fanout of non-leaf nodes of rcu_node combining tree. Default of 32 or 64 should work fine.

- **RCU_FANOUT_LEAF**: Control fanout of leaf nodes of rcu_node combining tree. Default of 16 should work fine.
  - Exception: Very large systems may need to set to 64, but only for kernels preceding v3.7.

- **RCU_FANOUT_EXACT=n**: Disabling rebalancing of rcu_node combining tree. Don't use pre-v3.14 if RCU_FANOUT and RCU_FANOUT_LEAF relatively prime...
Configuring RCU Combining-Tree Fanout

- **Root rcu_node structure**
  - **RCU_FANOUT(=2)**
  - **RCU_FANOUT_LEAF(=3)**

- **Leaf rcu_node structure**
  - CPU 0 rcu_data structure
  - CPU 1 rcu_data structure
  - CPU 2 rcu_data structure
  - CPU 3 rcu_data structure
  - CPU 4 rcu_data structure
  - CPU 5 rcu_data structure
Configuring RCU Combining-Tree Fanout

This choice is a really bad idea unless you have commit #e9c0e577...
Configuring RCU Combining-Tree Fanout

- RCU_FANOUT(=2)
- RCU_FANOUT_LEAF(=3)

Or RCU_FANOUT_EXACT=n. Which fortunately is the default.
RCU Kernel-Boot Parameters (1/3)

- `rcu_nocbs=:` List of CPUs to be NOCBs CPUs, but has no effect if RCU_NOCB_CPU_ALL.
- `rcu_nocb_poll(=n):` Avoid wakeup overhead in call_rcu() by making the rcu0 kthreads poll their CPU's callback lists.
- `rcutree.blimit(=10):` Maximum number of callbacks to invoke in a single batch from softirq.
- `rcutree.qhimark(=10,000):` Above this number of callbacks on a given CPU, ignore rcutree.blimit.
- `rcutree.qlowmark(=100):` Below this number of callbacks on a given CPU, revert to paying attention to rcutree.blimit.
- `rcutree.rcu_fanout_leaf:` Increase fanout vs. that specified by the RCU_FANOUT_LEAF Kconfig parameter.
RCU Kernel-Boot Parameters (2/3)

- `rcutree.jiffies_till_first_fqs`: Number of jiffies in an RCU grace period until the first check for dyntick-idle CPUs. Default is computed from HZ and `nr_cpu_ids`.
- `rcutree.jiffies_till_next_fqs`: Number of jiffies in an RCU grace period between checks for dyntick-idle CPUs. Default is computed from HZ and `nr_cpu_ids`.
- `rcutree.rcu_idle_gp_delay(=4)`: Number of jiffies till timed recheck for RCU_FAST_NO_HZ.
- `rcutree.rcu_idle_lazy_gp_delay(=6*HZ)`: Number of jiffies until timed recheck for RCU_FAST_NO_HZ if only lazy callbacks.
RCU Kernel-Boot Parameters (3/3)

- `rcupdate.rcu_expedited(=n)`: Use expedited grace period even when non-expedited primitives are invoked. Does not affect `call_rcu()` and friends.
- `rcupdate.rcu_cpu_stall_suppress(=n)`: Suppress reporting of any subsequent RCU CPU stall warning messages.
- `rcupdate.rcu_cpu_stall_timeout(=21)`: Set timeout in seconds for RCU CPU stall warnings.
- Plus lots of `rcutorture` settings. See the `rcutorture` source code for these.
Summary

- Synchronization overhead is a big issue for parallel programs
- Straightforward design techniques can avoid this overhead
  - Partition the problem: “Many instances of something good!”
  - Avoid expensive operations
  - Avoid mutual exclusion
- RCU is part of the solution
  - Excellent for read-mostly data where staleness and inconsistency OK
  - Good for read-mostly data where consistency is required
  - Can be OK for read-write data where consistency is required
  - Might not be best for update-mostly consistency-required data
  - Used heavily in the Linux kernel
- Careful RCU configuration helpful for real-time systems
Configuration Summary

- RCU_NOCB_CPU=y and RCU_NOCB_CPU_ALL=y to offload callback invocation.

- After changing code that uses RCU, please test with:
  - DEBUG_OBJECTS_RCU_HEAD(=n): Check for duplicate call_rcu() invocations
  - PROVE_RCU(=n): Check for accessing RCU-protected pointers outside of RCU read-side critical sections
  - SPARSE_RCU_POINTER(=n): When building with sparse, check usage of RCU-protected pointers.
Graphical Summary

Not only are they lazy, they get more work done than I do!
To Probe Further:

- [https://queue.acm.org/detail.cfm?id=2488549](https://queue.acm.org/detail.cfm?id=2488549)
  - “Structured Deferral: Synchronization via Procrastination” (also in July 2013 CACM)
- [http://doi.ieeecomputersociety.org/10.1109/TPDS.2011.159](http://doi.ieeecomputersociety.org/10.1109/TPDS.2011.159) and [http://www.computer.org/cms/Computer.org/dl/trans/td/2012/02/extras/ttd2012020375s.pdf](http://www.computer.org/cms/Computer.org/dl/trans/td/2012/02/extras/ttd2012020375s.pdf)
  - “User-Level Implementations of Read-Copy Update”
- [git://lttng.org/userspace-rcu.git](git://lttng.org/userspace-rcu.git) (User-space RCU git tree)
  - Applying RCU and weighted-balance tree to Linux mmap_sem.
  - RCU-protected resizable hash tables, both in kernel and user space
  - Combining RCU and software transactional memory
  - “What is RCU?” Series
  - RCU motivation, implementations, usage patterns, performance (micro+sys)
  - System-level performance for SELinux workload: >500x improvement
  - Comparison of RCU and NBS (later appeared in JPDC)
- [http://doi.acm.org/10.1145/1400097.1400099](http://doi.acm.org/10.1145/1400097.1400099)
  - History of RCU in Linux (Linux changed RCU more than vice versa)
  - Harvard University class notes on RCU (Courtesy of Eddie Koher)
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Questions?

Use the right tool for the job!!!