

Linux Kernel Scalability: Using the Right Tool for the Job

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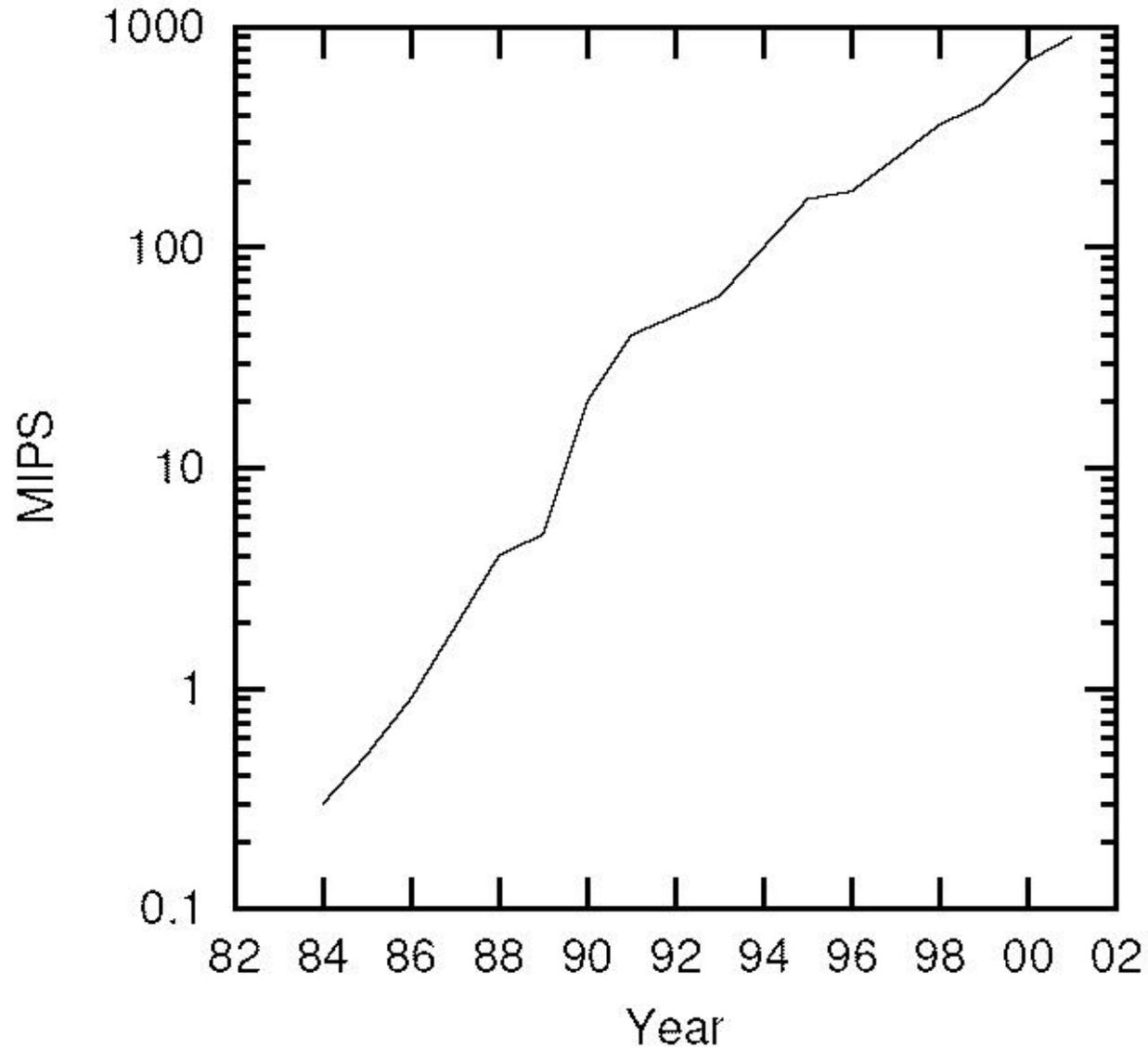
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Overview

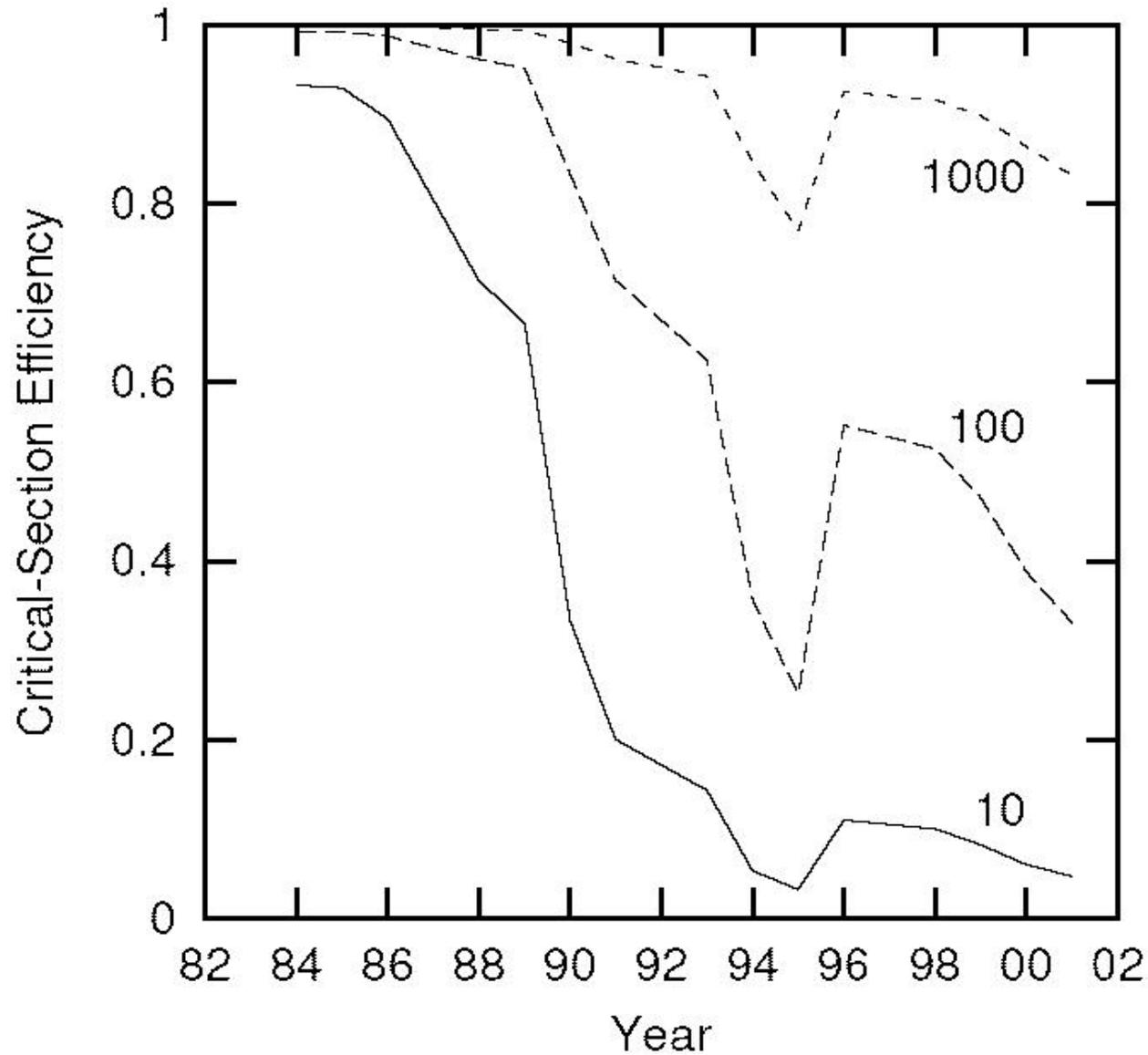
- Moore's Law and SMP Software
- Synchronization Usage
 - Locking, Counting, NBS, and RCU
 - Putting it All Together
- The Road Ahead
- Summary

Moore's Law and SMP Software

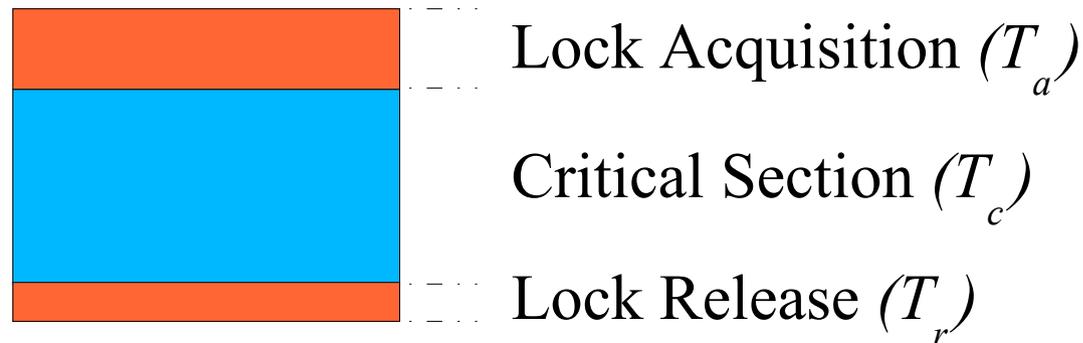
Instruction Speed Increased



Synchronization Speed Decreased



Critical-Section Efficiency



$$Efficiency = \frac{T_c}{T_c + T_a + T_r}$$

Assuming negligible contention and no caching effects in critical section

Instruction/Pipeline Costs on a 4-CPU 700MHz Pentium[®]-III

Operation	Nanoseconds
Instruction	0.7
Clock Cycle	1.4
L2 Cache Hit	12.9
Atomic Increment	58.2
Cmpxchg Atomic Increment	107.3
Atomic Incr. Cache Transfer	113.2
Main Memory	162.4
CPU-Local Lock	163.7
Cmpxchg Blind Cache Transfer	170.4
Cmpxchg Cache Transfer and Invalidate	360.9

Visual Demonstration of Latency

cmpxchg transfer & invalidate: 360.9ns

Each pair of nanoseconds represents
up to about three instructions

What is Going On? (1/3)

- Taller memory hierarchies
 - Memory speeds have not kept up with CPU speeds
 - 1984: no caches needed, since instructions slower than memory accesses
 - 2004: 3-4 level cache hierarchies, since instructions orders of magnitude faster than memory accesses
- Synchronization requires consistent view of data across CPUs, i.e., CPU-to-CPU communication
 - Unlike normal instructions, synchronization operations tend not to hit in top-level cache
 - Hence, they are orders of magnitude slower than normal instructions because of memory latency

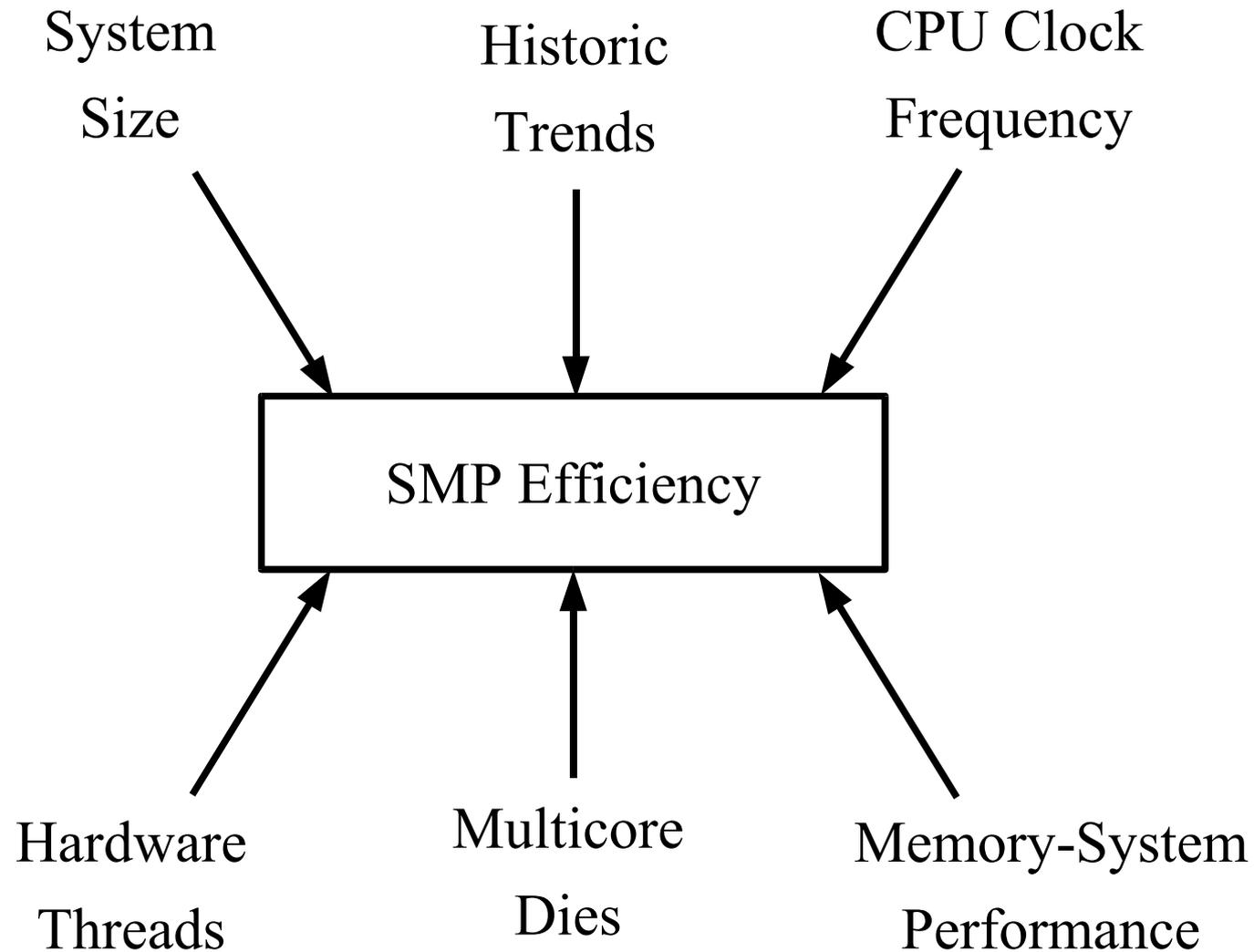
What is Going On? (2/3)

- Longer pipelines
 - 1984: Many clocks per instruction
 - 2004: Many instructions per clock – 20-stage pipelines
- Modern super-scalar CPUs execute instructions out of order in order to keep their pipelines full
 - Can't reorder the critical section before the lock!!!
- Therefore, synchronization operations must stall the pipeline, decreasing performance

What is Going On? (3/3)

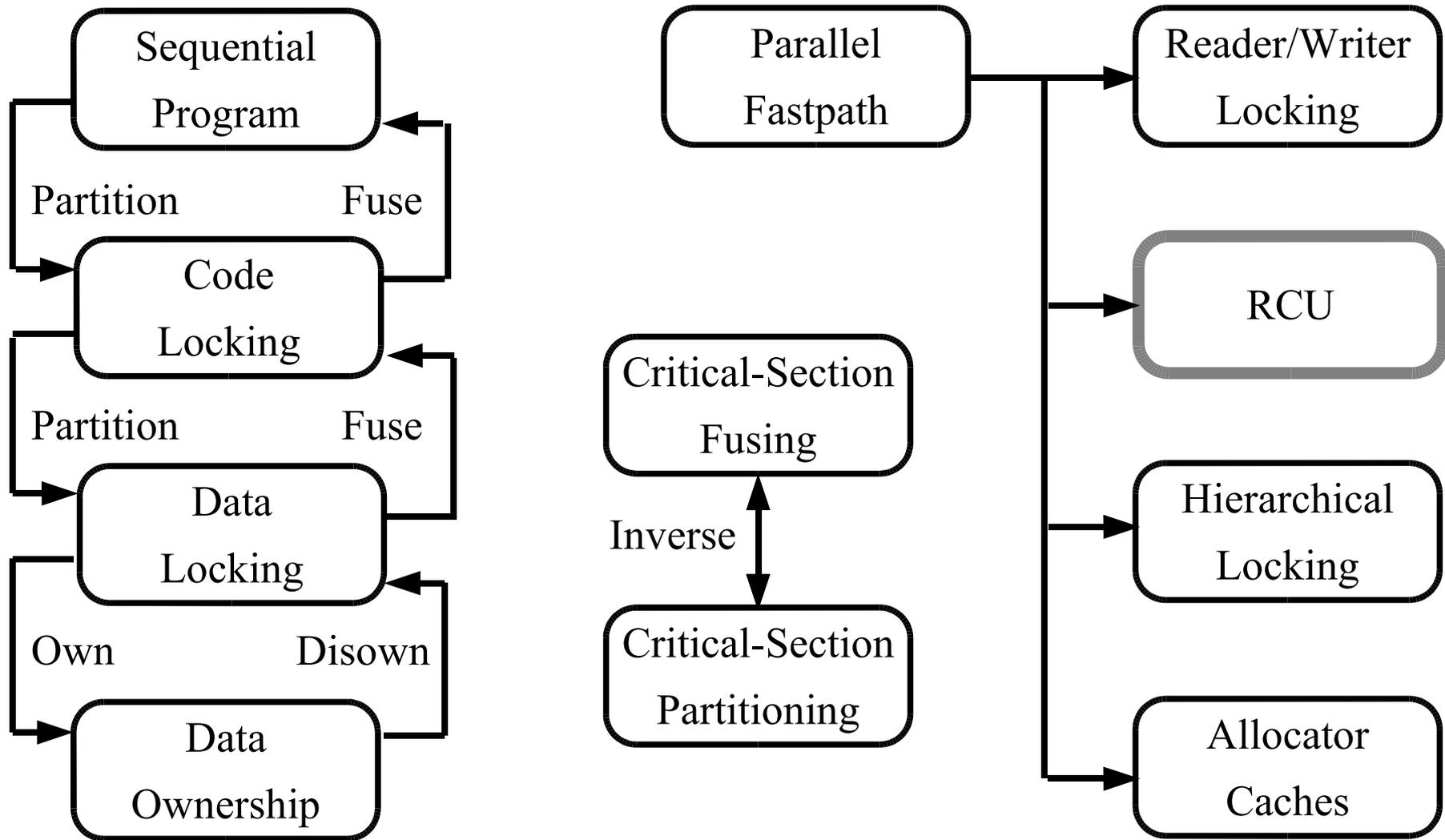
- 1984: The main issue was lock contention
- 2004: Even if lock contention is eliminated, critical-section efficiency must be addressed!!!
 - Even if the lock is *always* free when acquired, performance is seriously degraded

Forces Acting on SMP Efficiency



Locking

Locking Designs



Sequential Program

- If a single CPU can do the job you need, why are you messing with SMP and locking???
 - Not enough challenge in your life???
 - You like slowing things down by including SMP primitives?

Code Locking

- AKA “global locking”
 - Only one CPU at a time in given code path
- Very simple, but no scaling
- Examples:
 - 2.4 runqueue_lock
 - dcache_lock
 - Guards all dcache in 2.4, dcache updates in 2.6
 - rcu_ctrlblk.mutex

Data Locking

- But isn't it *all* data locking?
 - Yes, but... Data locking associates locks with individual data items rather than code paths
 - 2.4: “`spin_lock_irq(&runqueue_lock);`”
 - 2.6: “`spin_lock_irq(&rq->lock)`”
 - CPUs process different data items in parallel
- Examples:
 - 2.6 O(1) scheduler (per-runqueue locking)
 - 2.6 `d_lock` (per-dentry locking for path walking)
 - Manfred Spraul RCU_HUGE patch

Data Locking Implications (1)

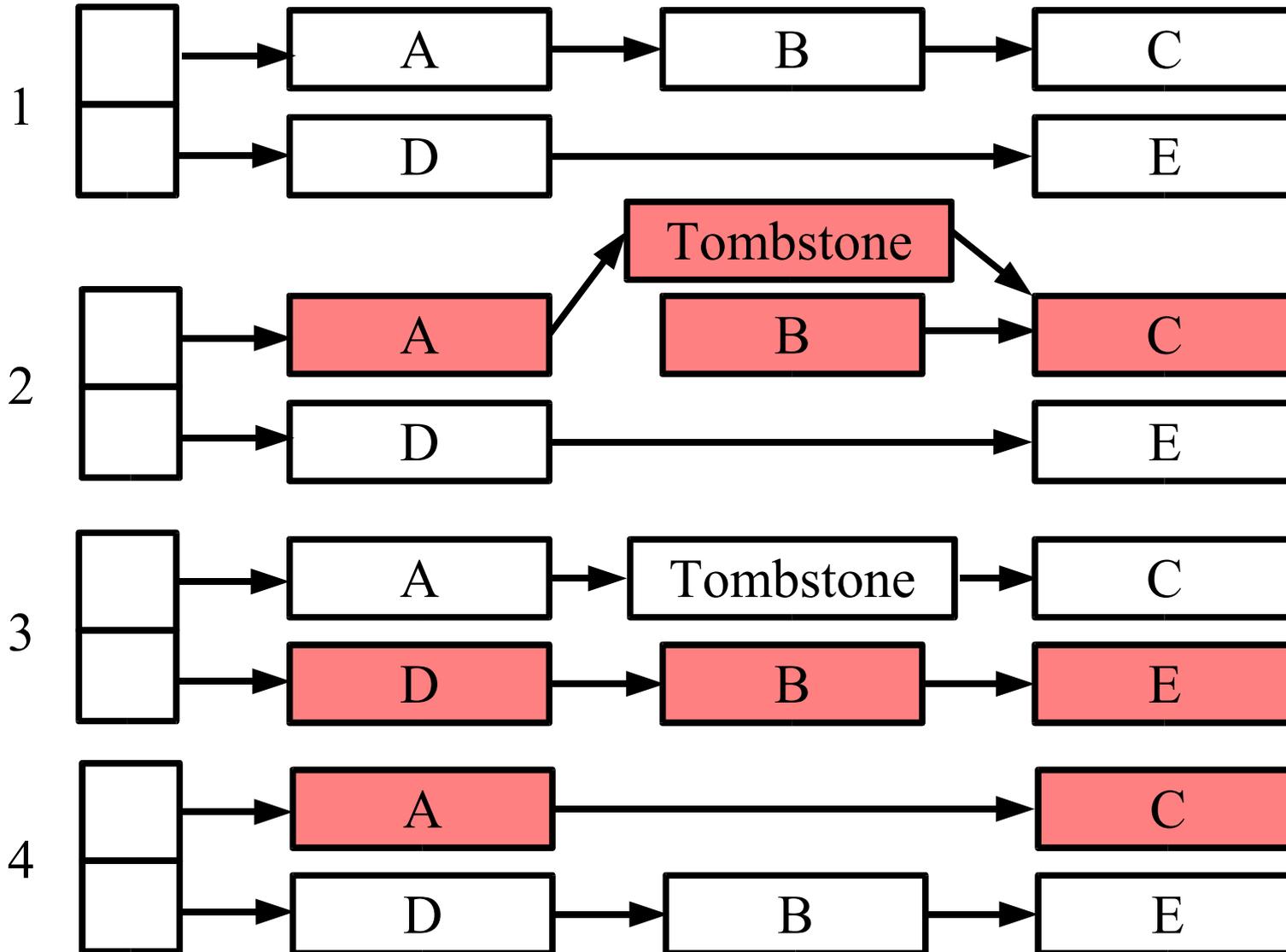
- How to handle common global structure?
 - Retain global lock for this purpose
 - dcache_lock retained when per-dentry d_lock added
 - Need both locks on many code paths
 - Restructure to eliminate common structure
 - Apply more aggressive locking model
- What if every CPU hits the same data item?
 - mm_lock is great – unless everyone is faulting on the same shared-memory segment...

Data Locking Implications (2)

- How to handle two data items concurrently?
 - Acquire locks in order: `d_move()` in `dcache`:

```
if (target < dentry) {
    spin_lock(&target->d_lock);
    spin_lock(&dentry->d_lock);
} else {
    spin_lock(&dentry->d_lock);
    spin_lock(&target->d_lock);
}
```
 - Acquire multiple locks only if holding global lock
 - Careful!!! The use of a global lock can easily wipe out any data-locking performance gains!
 - Figure out a way to handle one item at a time

Data Locking: One at a Time



Data Ownership

- `DEFINE_PER_CPU(type, name)`
 - But it is possible to access others' variables via `per_cpu(var, cpu)`
 - Used during initialization
 - Also for reading out performance statistics
 - IA64 `pfm_proc_show()`
 - PPC64 `proc_eeh_show()`
 - And for coordinating CPUs
 - IA64 `wrap_mmu_context()`

Data Ownership Implications

- Data completely private to owning CPU
 - Used pervasively throughout Linux kernel
- Incomplete privacy:
 - Owning CPU updates, others read
 - Statistics (next slide)
 - Other CPUs update only if owning CPU offline
 - Didn't see any, may have missed some...
 - Owning CPU reads, others update (via sysfs)
 - `store_smt_snooze_delay()`

Owning CPU Updates

- TCP stats gathered via IP_INC_STATS_BH
- TCP stats readout

```
static unsigned long
__fold_field(void *mib[], int offt)
{
    unsigned long res = 0;
    int i;
    for (i = 0; i < NR_CPUS; i++) {
        if (!cpu_possible(i))
            continue;
        res += *((unsigned long *)(((void *)per_cpu_ptr(mib[0], i)) +
            offt));
        res += *((unsigned long *)(((void *)per_cpu_ptr(mib[1], i)) +
            offt));
    }
    return res;
}
```

Owning CPU Reads

- PPC64 idle-loop control of hardware threads

```
unsigned long start_snooze;
unsigned long *smt_snooze_delay = &__get_cpu_var(smt_snooze_delay);
while (1) {
    oldval = test_and_clear_thread_flag(TIF_NEED_RESCHED);
    if (!oldval) {
        set_thread_flag(TIF_POLLING_NRFLAG);
        start_snooze = __get_tb() +
            *smt_snooze_delay * tb_ticks_per_usec;
        while (!need_resched()) {
            if (*smt_snooze_delay == 0 ||
                __get_tb() < start_snooze) {
                HMT_low(); /* Low thread priority */
                continue;
            }
            HMT_very_low(); /* Low power mode */
        }
        . . .
    }
}
```

Data Ownership: Function Shipping

- mm/slab.c

```
static void do_drain(void *arg)
{
    kmem_cache_t *cachep = (kmem_cache_t*)arg;
    struct array_cache *ac;
    check_irq_off();
    ac = ac_data(cachep); /* Returns ptr to per-CPU element. */
    spin_lock(&cachep->spinlock);
    free_block(cachep, &ac_entry(ac)[0], ac->avail);
    spin_unlock(&cachep->spinlock);
    ac->avail = 0;
}
static void drain_cpu_caches(kmem_cache_t *cachep)
{
    smp_call_function_all_cpus(do_drain, cachep);
    . . .
}
```

Parallel Fastpath

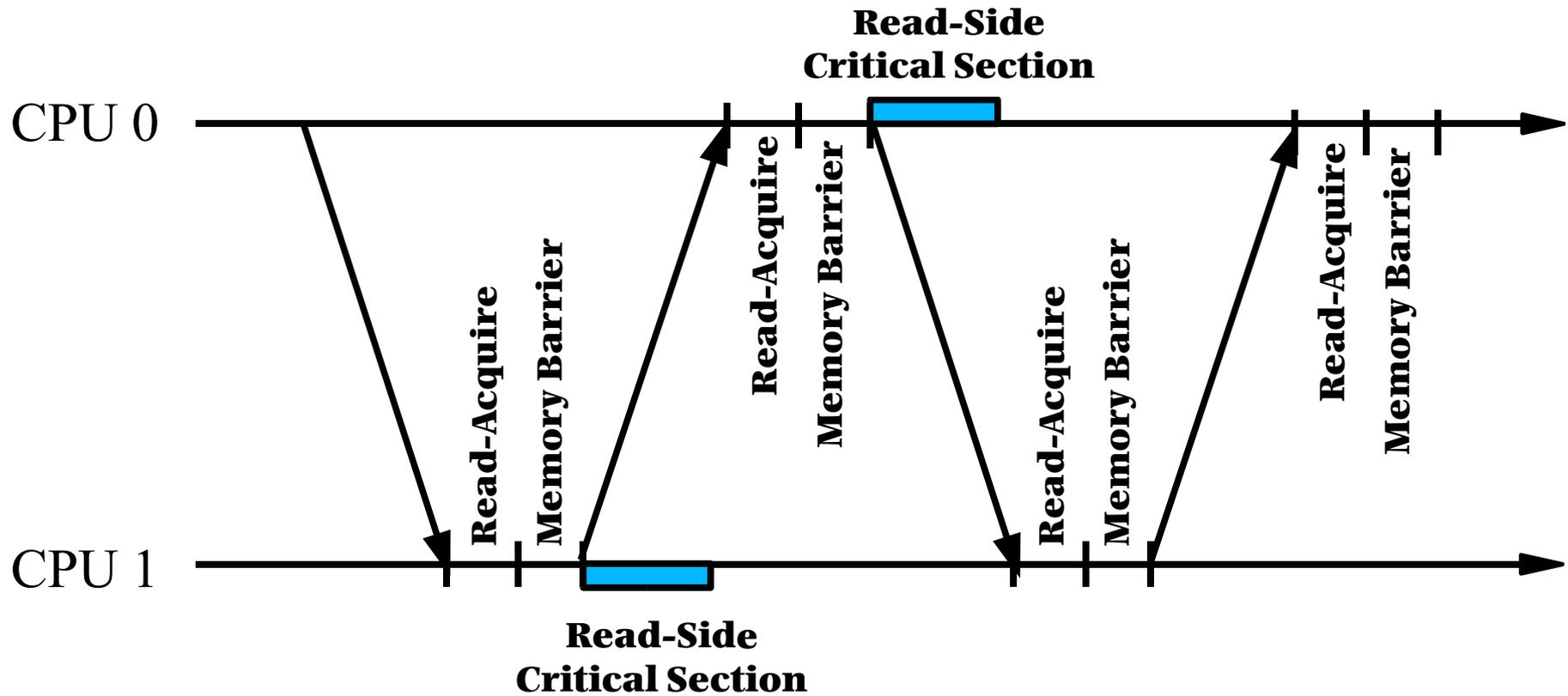
- Make the common case fast, the uncommon case as simple as possible
 - Reader-writer locking
 - RCU (more on this later...)
 - Hierarchical locking
 - Allocator caches

Reader-Writer Locking

- Use for large read-side critical sections.
- `get_task()` is an example of good usage
 - Might have 1000s of processes
 - Releases lock before returning pointer...

```
read_lock(&tasklist_lock);
for_each_process(task){
    if(task->pid == pid){
        ret = task;
        break;
    }
}
read_unlock(&tasklist_lock);
```

Do Not Use `rwlock_t` for Short Read-Side Critical Sections



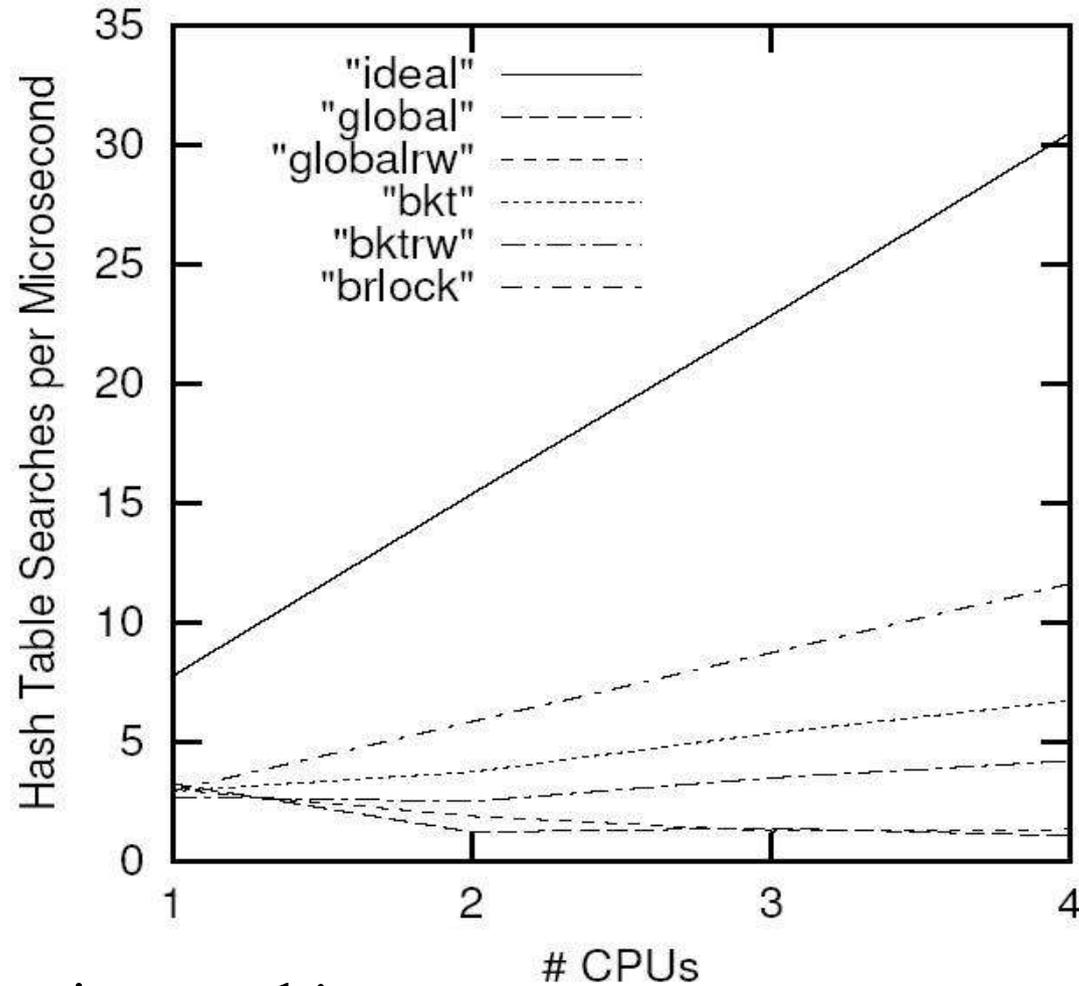
Performance Comparison: What Benchmark to Use?

- Focus on operating-system kernels
 - Many read-mostly hash tables
- Hash-table mini-benchmark
 - Dense array of buckets
 - Doubly-linked hash chains
 - One element per hash chain
 - You do tune your hash tables, don't you???

How to Evaluate Performance?

- Mix of operations:
 - Search
 - Delete followed by reinsertion: maintain loading
 - Random run lengths selected for specified mix
 - (See thesis)
- Start with pure search workload (read only)
- Run on 4-CPU 700MHz P-III system
 - Single quad Sequent[®]/IBM[®] NUMA-Q[®] system

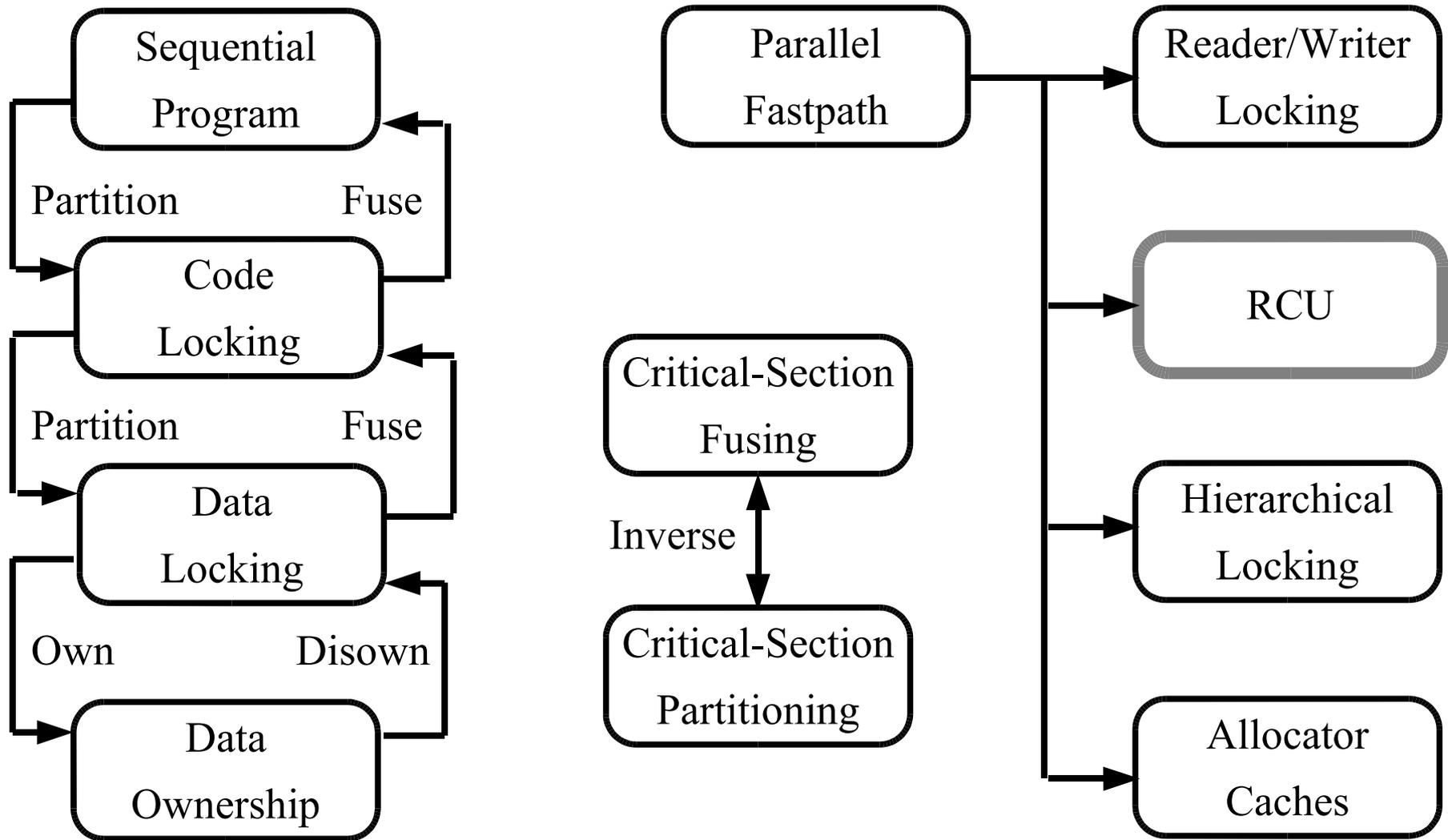
Locking Performance



Extra CPUs not buying much!

Note: workload fits in cache.

Locking Designs



Counting

Counters: Workload Dependent

- No blocking while holding or releasing count
- Updates rare (just use a global counter!!!)
- Updates common:
 - References rare:
 - “Fuzzy” readout permissible
 - Exact readout required
 - References frequent:
 - Just use seqlock_t!!!
 - Memory-barrier/atomic overhead too much and large value
 - “Fuzzy” readout permissible
 - References are checks for rarely exceeded range
- Otherwise, innovation required

Updates Common, References Rare (1)

- Statistical counters!!! Per-CPU counters...
- Fuzzy readout: just need to manage value
 - Reference released on same CPU as acquired (or monotonic counters)
 - Simple per-CPU counters, sum them without lock
 - See previous data-ownership example
 - CPUs can release other CPUs' references
 - Need to migrate counts in some cases
 - For example, if it is important to detect zero crossings
 - Rusty has been working on a prototype, crude version here

Updates Common, References Rare (2)

- Exact readout at arbitrary time and value?
- Must stall readers... And add complexity...
 - `br_read_lock()` to update counter, `br_write_lock()` to read counter (can use `per_cpu()` in 2.6)
 - Moderate latency for readout
 - Moderate overhead for read
 - RCU and flags, readers block if flag set
 - Untried, not clear this is a good approach
- Friendly advice: tolerate uncertainty!!!

brlock Counter

```
/* Increment counter. */
br_read_lock(BR_MY_LOCK);
__get_cpu_var(my_count)++;
br_read_unlock(BR_MY_LOCK);

/* Read out counter. */
br_write_lock(BR_MY_LOCK);
for_each_cpu(i)
    sum += per_cpu(my_count, i);
br_write_unlock(BR_MY_LOCK);
```

- Yes, you do read-acquire the lock to write the variable and vice versa!!!
- We are really using (abusing!) the brlock as a local-global rather than a reader-writer lock

2.6 Implementation of brlock Counter

```
/* Increment counter. */
spin_lock(__get_cpu_var(mylock));
__get_cpu_var(mycount)++;
spin_unlock(__get_cpu_var(mylock));

/* Read out counter. */
for_each_cpu(i) {
    spin_lock(per_cpu(mylock, i));
    sum += per_cpu(mycount, i);
}
for_each_cpu(i) {
    spin_unlock(per_cpu(mylock, i));
}
```

- A few more lines of on the read-out side, but two rather than three loops
- Inline functions helpful if frequently used

“Big Reference Count”

- Maintain per-CPU counters
- But also provide a global counter
 - Value is sum of all counters
 - Ship counts between per-CPU and global count
 - Apply a large bias to the count
- Use the per-CPU counters in fastpath
- When checking for zero, remove the bias
 - Force use of only global counter

Big Reference Count Data

- Per-CPU component

```
struct brefcnt_percpu {  
    int    brcp_count;    /* Per- CPU ctr. Should interlace */  
}
```

- Global component

```
struct brefcnt {  
    spinlock_t brc_mutex; /* Guards all but brc_percpu. */  
    long    brc_global;    /* Global portion of count. */  
    void    (*brc_zero)(struct brefcnt *r, void *arg);  
                                /* Function to call zero count. */  
    void    *brc_arg;      /* 2nd argument for brc_zero. */  
    struct brefcnt_percpu *brc_percpu ____cacheline_aligned;  
    int    brc_local;     /* 1=use local counts, 0=use gbl. */  
};
```

- Converging with krefcnt would be challenge!!!

Big Reference Count Increment

```
void brefcnt_inc(struct brefcnt *r)
{
    int val;

    if (likely(r->brc_local)) {
        val = r->brc_percpu[smp_processor_id()].brcp_count++;
        if (unlikely(val > 2 * BREFCNT_PER_CPU_TARGET)) {
            r->brc_percpu[smp_processor_id()].brcp_count
                -= BREFCNT_PER_CPU_TARGET;
            spin_lock(&r->brc_mutex);
            r->brc_global += BREFCNT_PER_CPU_TARGET;
            spin_unlock(&r->brc_mutex);
        }
        return;
    }
    spin_lock(&r->brc_mutex);
    r->brc_global++;
    spin_unlock(&r->brc_mutex);
}
```

Big Reference Count Decrement

```
void brefcnt_dec(struct brefcnt *r)
{
    long val;
    int *pcp = &r->brc_percpu[smp_processor_id()].brcp_count;
    if (likely(r->brc_local)) {
        if (*pcp > 1) {
            (*pcp)--;
            return;
        }
        spin_lock(&r->brc_mutex);
        r->brc_global -= BREFCNT_PER_CPU_TARGET;
        spin_unlock(&r->brc_mutex);
        *pcp += BREFCNT_PER_CPU_TARGET - 1;
        return;
    }
    spin_lock(&r->brc_mutex);
    val = --r->brc_global;
    spin_unlock(&r->brc_mutex);
    if ((val == 0) && (r->brc_zero != NULL)) {
        r->brc_zero(r, r->brc_arg);
    }
}
```

Big Refcount Remove Bias

```
void brefcnt_remove_bias(struct brefcnt *r)
{
    int i;
    long val;

    spin_lock(&r->brc_mutex);
    r->brc_local = 0;
    spin_unlock(&r->brc_mutex);

    synchronize_kernel(); /* wait for racing incs/ decs. */

    spin_lock(&r->brc_mutex);
    for_each_cpu(i) {
        r->brc_global += r->brc_percpu[i].brcp_count;
        r->brc_percpu[i].brcp_count = 0;
    }
    val = (r->brc_global -= BREFCNT_BIAS);
    spin_unlock(&r->brc_mutex);
    if ((val == 0) && (r->brc_zero != NULL))
        r->brc_zero(r, r->brc_arg);
}
```

Updates Rare, References Common

- Just use `seqlock_t`!
- Unless you cannot afford the atomic-instruction and memory-barrier overhead
 - If you really believe you cannot afford the atomic-instruction and memory-barrier overhead, do the measurements again, and *carefully* analyze the results!!!
 - If you really cannot afford this, you can use big reference count in some special cases

seqlock_t Timer Handling

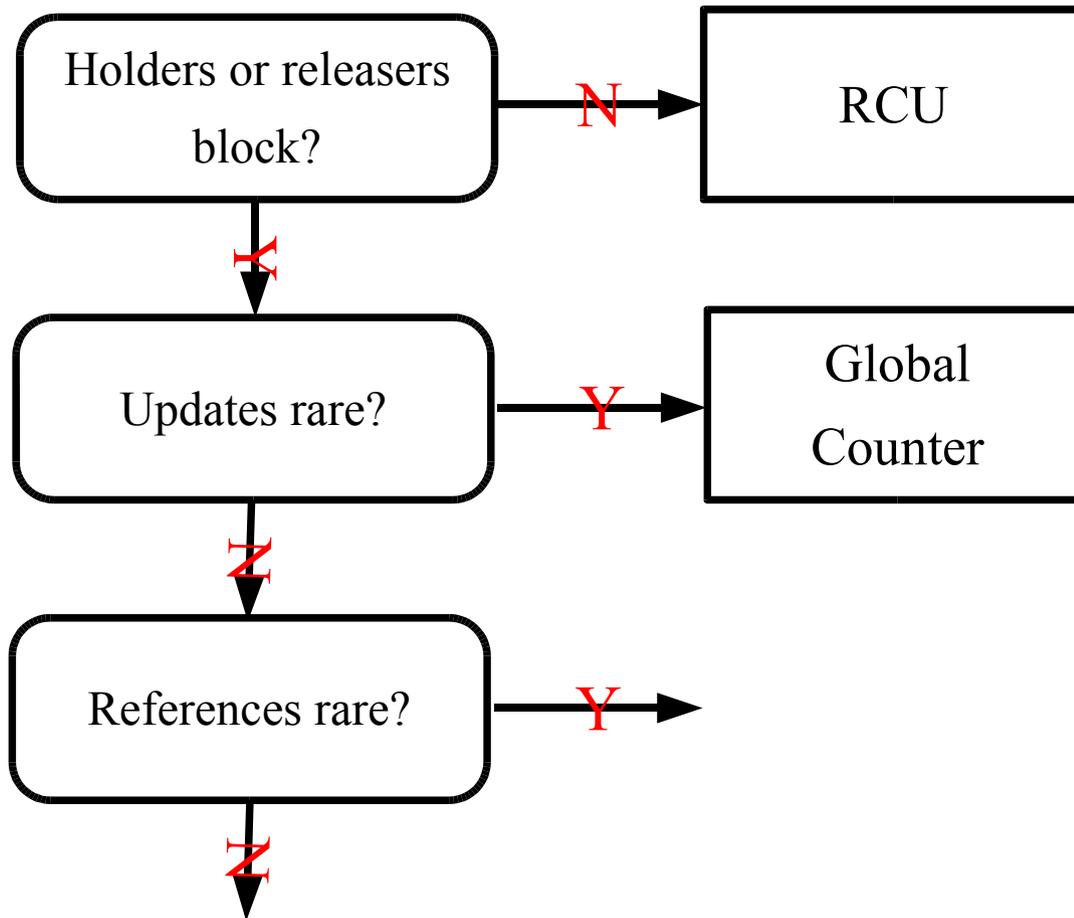
- Timer update

```
write_seqlock(&xtime_lock);  
cur_timer->mark_offset();  
do_timer_interrupt(irq, NULL, regs);  
write_sequnlock(&xtime_lock);
```

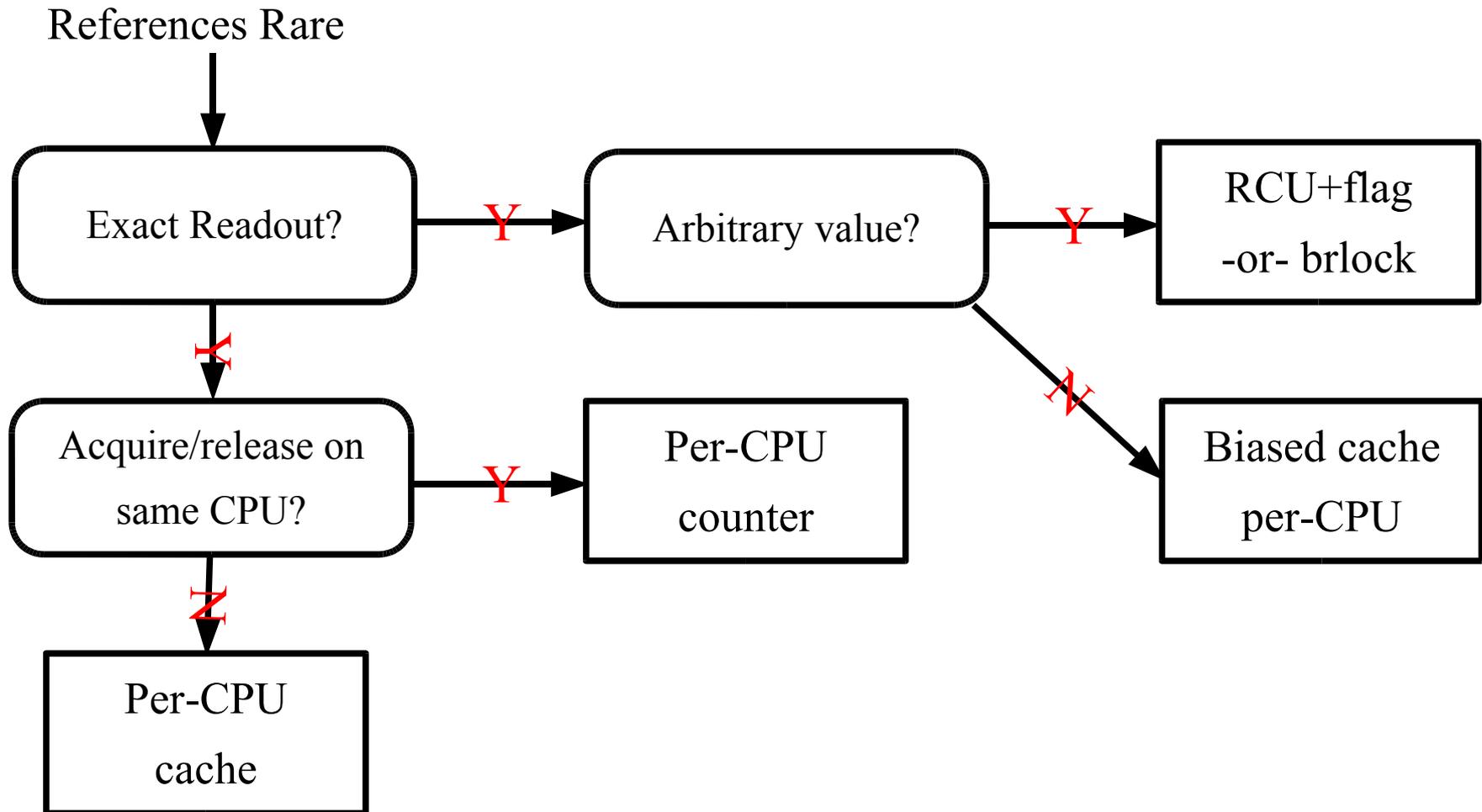
- Timer readout

```
do {  
    seq = read_seqbegin_irqsave(&xtime_lock, flags);  
    delta_cycles = rpcc() - state.last_time;  
    sec = xtime.tv_sec;  
    usec = (xtime.tv_nsec / 1000);  
    partial_tick = state.partial_tick;  
    lost = jiffies - wall_jiffies;  
} while (read_seqretry_irqrestore(&xtime_lock, seq, flags));
```

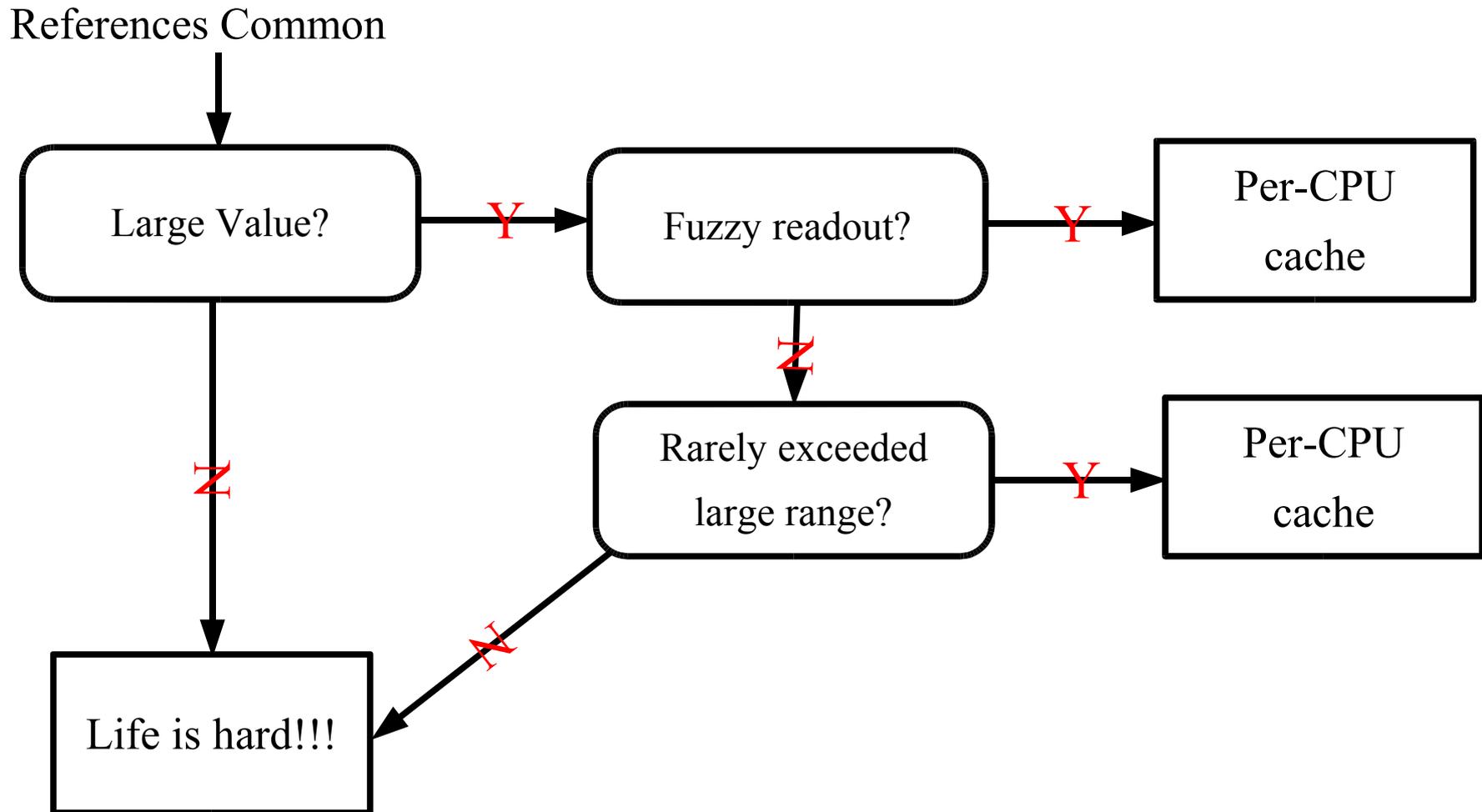
Counter Decision Tree



Counter Decision Tree (Rare Ref)



Counter Decision Tree (Many Ref)



Other Counter Complications

- 64-bit counters on 32-bit machine
- Access from both irq and process context
 - Preemption can have similar effects...
- Need to update other CPUs' counters
- Need agreement on sequence of values
 - Parallel increments of 1, 5, and 7
 - 1, 6, 13? 5, 12, 13? 7, 8, 13?
 - Friendly advice: tolerate dissent!!!

Non-Blocking Synchronization (NBS)

What About Non-Blocking Synchronization?

- What is non-blocking synchronization (NBS)?
 - Roll back to resolve conflicting changes instead of spinning or blocking
 - Uses atomic instructions to hide complex updates behind a single commit point
 - Readers and writers use atomic instructions such as compare-and-swap or LL/SC
- Simple “NBS” algorithms in heavy use
 - Atomic-instruction-based algorithms

Why Not NBS All The Time?

Operation	Nanoseconds
Instruction	0.7 ←
Clock Cycle	1.4
L2 Cache Hit	12.9
Atomic Increment	58.2
Cmpxchg Atomic Increment	107.3 ←
Atomic Incr. Cache Transfer	113.2 ←
Main Memory	162.4
CPU-Local Lock	163.7
Cmpxchg Blind Cache Transfer	170.4 ←
Cmpxchg Cache Transfer and Invalidate	360.9 ←

When to Use NBS?

- Simple NBS algorithm is available
 - Counting (strictly speaking, only by 1)
 - See example from previous section
 - Simple queue/stack management
 - Especially if NBS constraints may be relaxed!
- Workload is update-heavy
 - So that NBS's use of atomic instructions and memory barriers is not causing gratuitous pain

NBS Constraints

- Progress guarantees in face of task failure
 - Everyone makes progress: wait free
 - Someone makes progress: lock free
 - Someone makes progress in absence of contention: obstruction free
- “Linearizability”
 - All CPUs agree on all intermediate states
- Both constraints mostly irrelevant to Linux

RCU

What is RCU? (1)

- Reader-writer synchronization mechanism
 - Best for read-mostly data structures
- Writers create new versions atomically
 - Normally create new and delete old elements
- Readers can access old versions independently of subsequent writers
 - Old versions garbage-collected, deferring destruction
 - Readers must signal GC when done

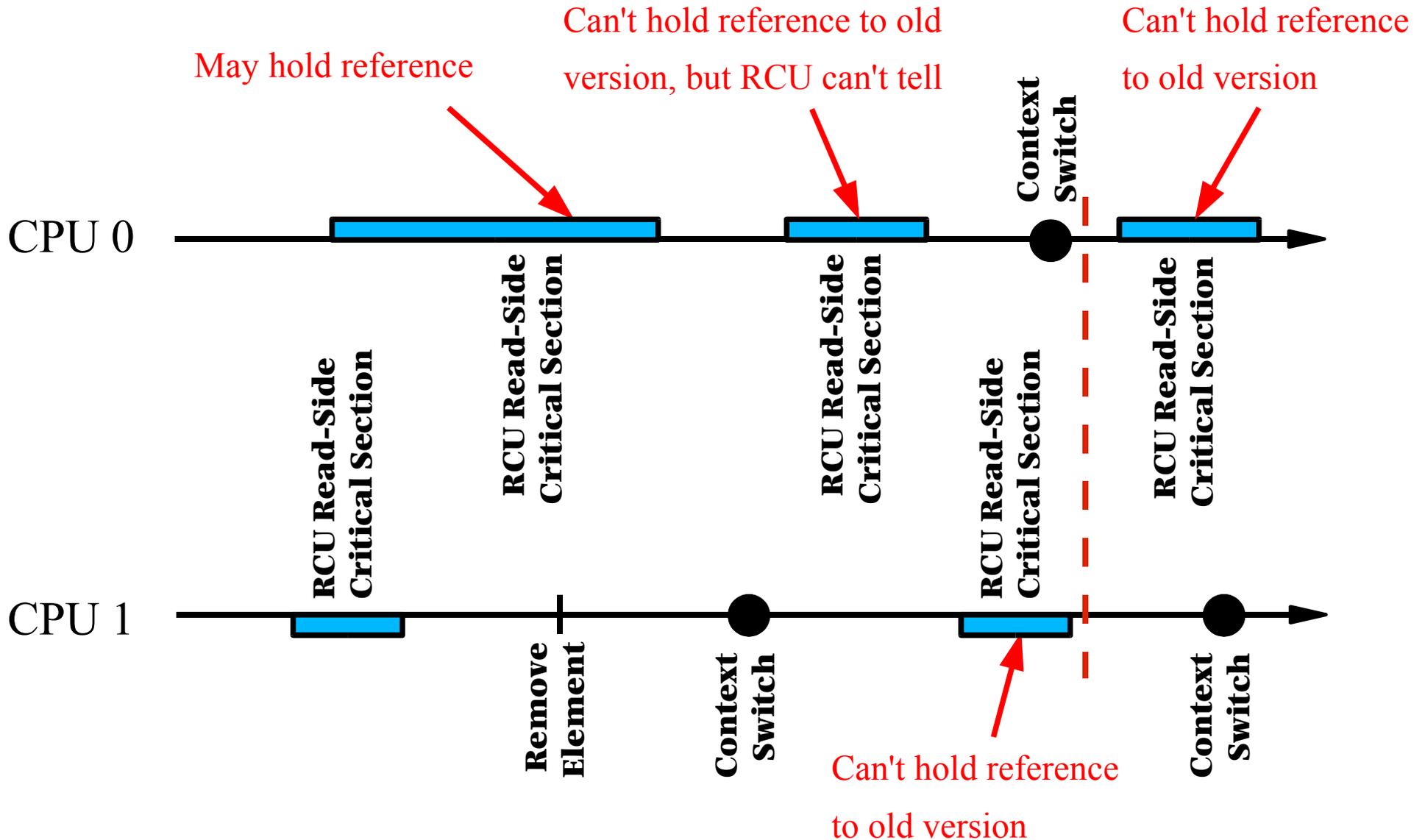
What is RCU? (2)

- Readers incur little or no overhead
- Writers incur substantial overhead
 - Writers must synchronize with each other
 - Writers must defer destructive actions until readers are done
 - The “poor man's” garbage collector also incurs some overhead

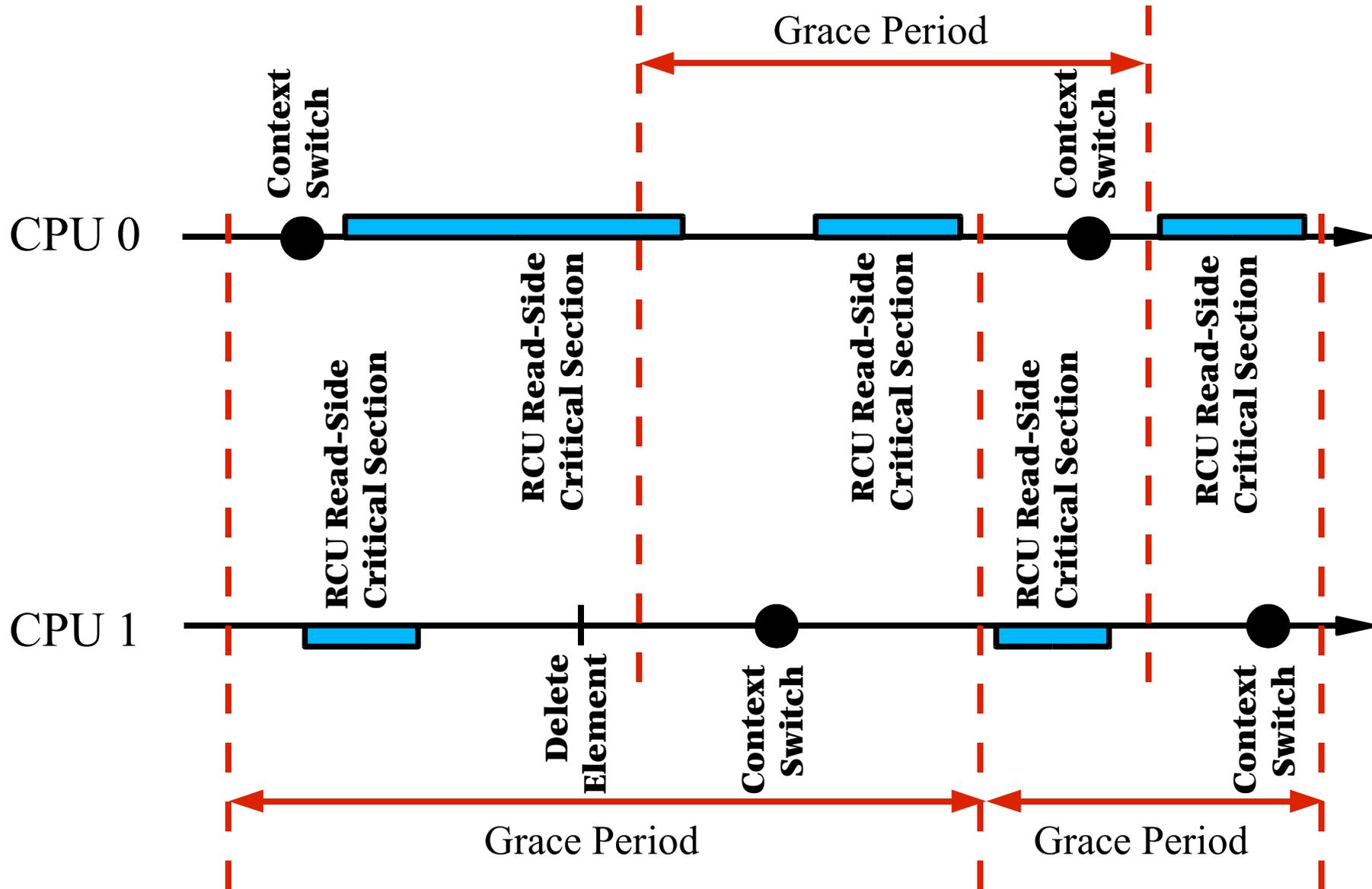
How Can RCU be Fast?

- Piggyback notification of reader completion on context-switch (and similar events)
- Kernels are usually constructed as event-driven systems, with short-duration run-to-completion event handlers
 - Greatly simplifies deferring destruction because readers are short-lived
 - Permits tight bound on memory overhead
 - Limited number of versions waiting to be collected

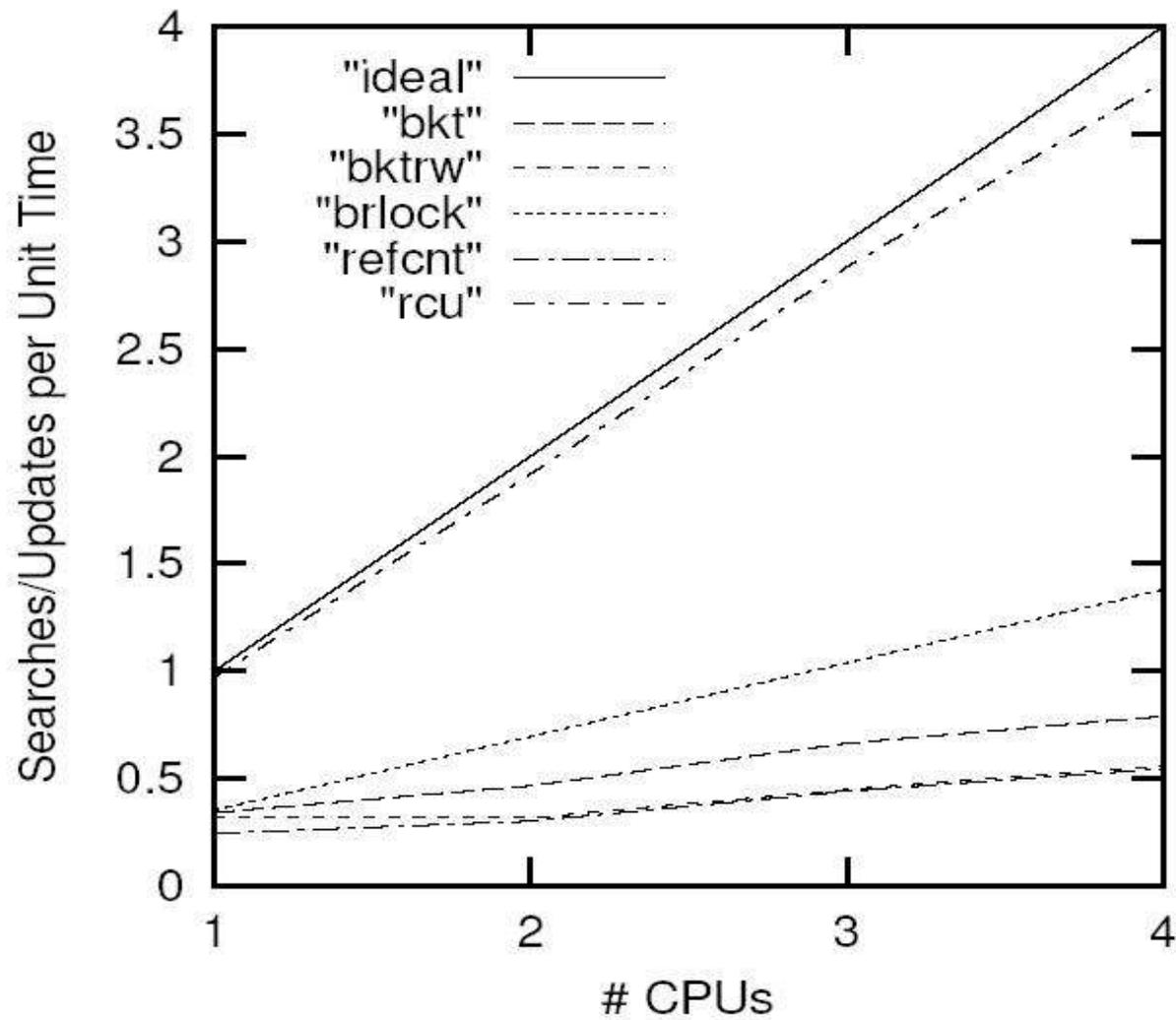
RCU's Deferred Destruction



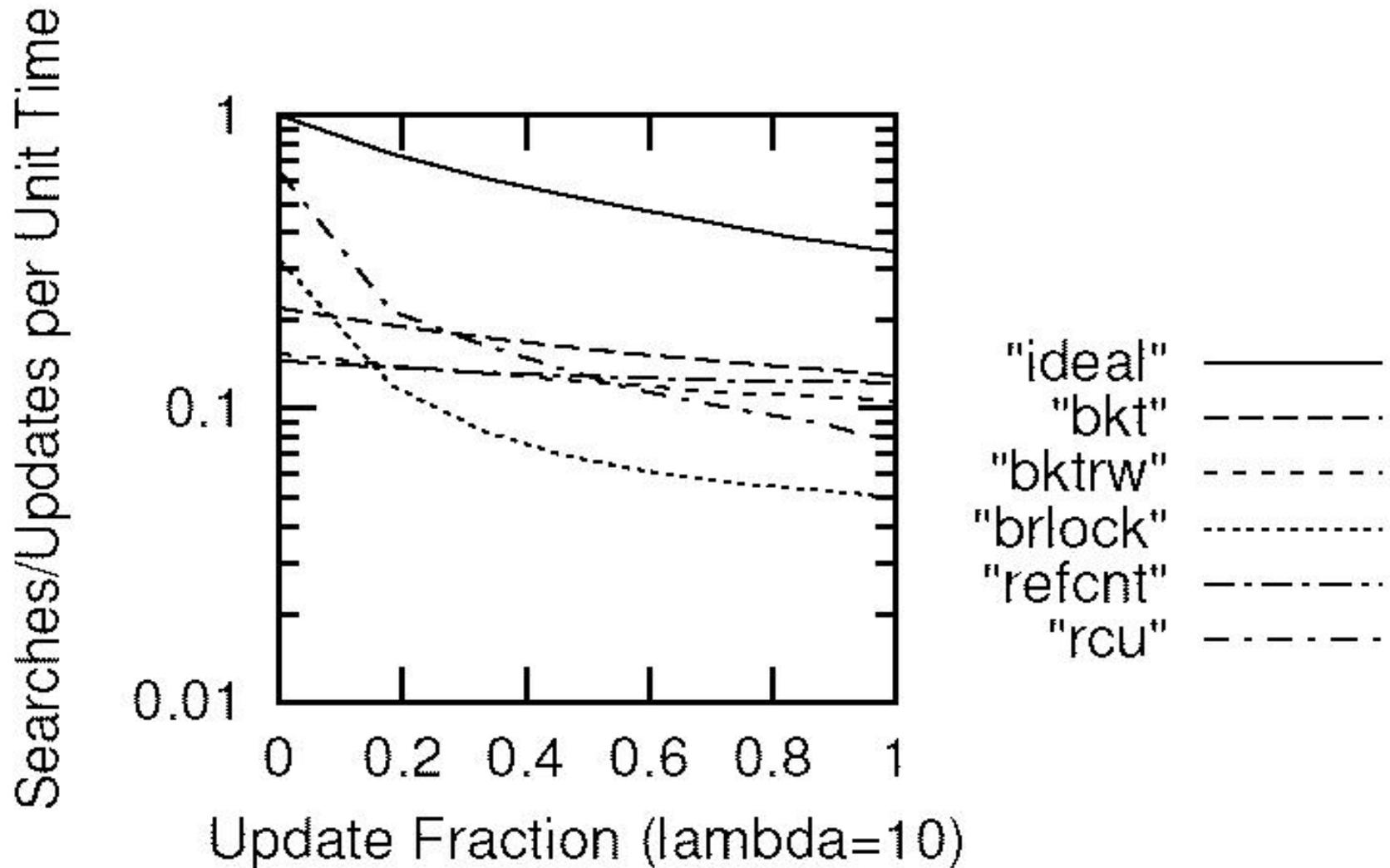
Grace Periods



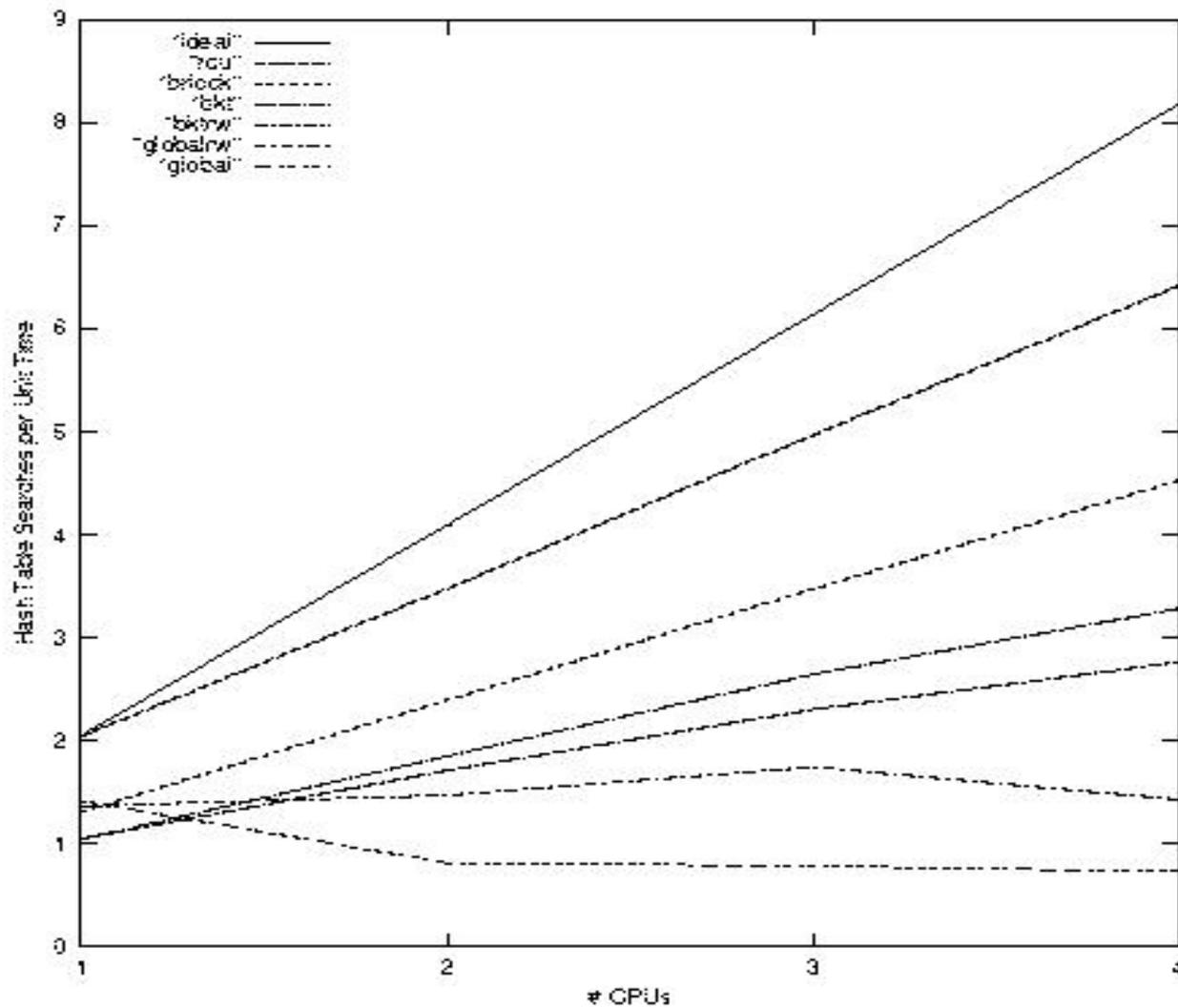
x86 Read-Only Results



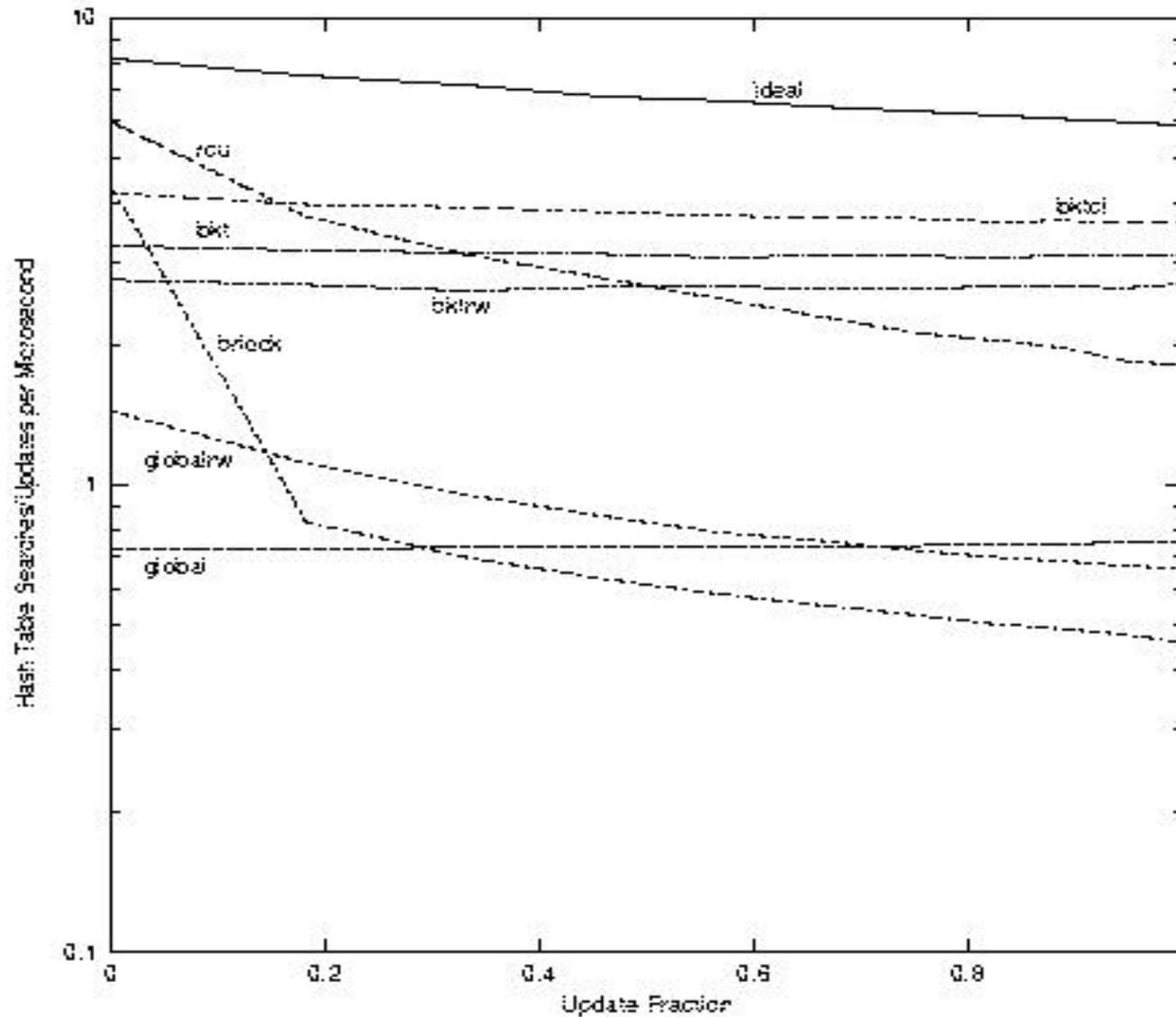
x86 Results for Mixed Workload



x86 Read-Only Results (Large)



x86 Mixed Results (Large)



Two Types of Designs For RCU

- For situations well-suited to RCU:
 - Designs that make direct use of RCU
- For algorithms that do not tolerate RCU's stale-and inconsistent-data properties:
 - Design templates that transform algorithms so as to tolerate stale and/or inconsistent data

Designs for Direct RCU Use

- Reader/Writer-Lock/RCU Analogy (5)
 - Routing tables, Linux tasklist lock patch, ...
- Pure RCU (4)
 - Dynamic interrupt handlers...
 - Linux NMI handlers...
- RCU Existence Locks (7)
 - Ensure data structure persists as needed (K42)
 - Linux SysV IPC, dcache, IP route cache, ...
- RCU Readers With WFS Writers (1)
 - K42 hash tables

Reader/Writer-Lock/RCU Analogy

- read_lock()
- read_unlock()
- write_lock()
- write_unlock()
- list_add()
- list_del()
- free(p)
- rcu_read_lock()
- rcu_read_unlock()
- spin_lock()
- spin_unlock()
- list_add_rcu()
- list_del_rcu()
- call_rcu(free, p)

Reader-Writer Lock and RCU

```
int search(long key, int result)
{
    struct el *p;
    read_lock(&rw);
    list_for_each_entry(h, p, lst)
        if (p->key == key) {
            *result = p->data;
            read_unlock(&rw);
            return (1);
        }
    read_unlock(&rw);
    return (0);
}
```

```
int search(long key, int result)
{
    struct el *p;
    rcu_read_lock();
    list_for_each_entry_rcu(h, p, lst)
        if (p->key == key) {
            *result = p->data;
            rcu_read_unlock();
            return (1);
        }
    rcu_read_unlock();
    return (0);
}
```

Reader-Writer Lock and RCU

```
int delete(long key)
{
    struct el *p;
    write_lock(&rw);
    list_for_each_entry(h, p, lst)
        if (p->key == key) {
            list_del(&p->lst);
            write_unlock(&rw);
            return (1);
        }
    write_unlock(&rw);
    return (0);
}
```

```
int delete(long key)
{
    struct el *p;
    spin_lock(&lck);
    list_for_each_entry(h, p, lst)
        if (p->key == key) {
            list_del_rcu(&p->lst);
            spin_unlock(&lck);
            return (1);
        }
    spin_unlock(&lck);
    return (0);
}
```

Reader-Writer Lock and RCU

```
void insert(struct el *p)
{
    write_lock(&rw);
    list_add(p, h);
    write_unlock(&rw);
}
```

```
void insert(struct el *p)
{
    spin_lock(&lck);
    list_add_rcu(p, h);
    spin_unlock(&lck);
}
```

RCU/Reader-Writer-Lock Caveats

- Searches race with updates
 - Some algorithms tolerate such nonsense
 - Others need to be transformed – see later slides
- Updaters still can see significant contention
 - See earlier locking designs
- There is no way to block readers
 - Which is the whole point...
 - See later slides for ways to deal with this

Pure RCU

- Delay execution of update until all existing readers are done
 - See prior “big reference counter” example
 - The dynamic NMI/SMI/IPMI handlers are another example

Pure RCU: Timeouts and Interrupts

```
spin_lock_irqsave(&(to_clean->si_lock), flags);
spin_lock(&(to_clean->msg_lock));
to_clean->stop_operation = 1;
to_clean->irq_cleanup(to_clean);
spin_unlock(&(to_clean->msg_lock));
spin_unlock_irqrestore(&(to_clean->si_lock), flags);

synchronize_kernel();
while (!to_clean->timer_stopped) {
    set_current_state(TASK_UNINTERRUPTIBLE);
    schedule_timeout(1);
}
rv = ipmi_unregister_smi(to_clean->intf);
if (rv)
    printk(KERN_ERR "Can't unregister device: errno=%d\n", rv);

to_clean->handlers->cleanup(to_clean->si_sm);
kfree(to_clean->si_sm);
to_clean->io_cleanup(to_clean);
```

RCU Existence Locks

- Normal existence-guarantee schemes use global locks or per-element reference counts
 - Subject to contention and cache thrashing
 - But reference counts are OK if you need to write to the element anyway!
- RCU provides existence guarantees

```
list_del_rcu(p);  
synchronize_kernel();  
kfree(p);
```

Designs for Direct RCU Use

- Reader/Writer-Lock/RCU Analogy (5)
- Pure RCU (4)
- RCU Existence Locks (7)
- RCU Readers With WFS Writers (1)
 - Only one use thus far, ask me again later!
- But what about algorithms that don't like stale data???

Stale and Inconsistent Data

- RCU allows concurrent readers and writers
 - RCU allows readers to access old versions
 - Newly arriving readers will get most recent version
 - Existing readers will get old version
 - RCU allows multiple simultaneous versions
 - A given reader can access different versions while traversing an RCU-protected data structure
 - Concurrent readers can be accessing different versions
- Some algorithms tolerate this consistency model, but many do not

RCU Transformational Templates

- Substitute Copy for Original
- Impose Level of Indirection
- Mark Obsolete Objects
- Ordered Update With Ordered Read
- Global Version Number
- Stall Updates

Substitute Copy For Original

- RCU uses atomic updates of single value
 - Most CPUs support this
- If multiple updates must appear atomic:
 - Must hide updates behind a single atomic operation in order to apply RCU
- To provide atomicity:
 - Make a copy, update the copy, then substitute the copy for the original
- Example in next section

Impose Level of Indirection

- Difficult to ensure consistent view of multiple independent data elements
 - Requires lots and lots of memory barriers
- Solution: place the independent data elements in one structure referenced by a pointer
- Then can atomically switch the pointer
 - And get rid of most of the memory barriers!!!
- Example in next section

Mark Obsolete Object

- RCU search structure w/data-locked items

```
rcu_read_lock();  
p = search(key);  
if (p != NULL)  
    spin_lock(&p->mutex);  
rcu_read_unlock();
```

- Place a “deleted” flag in each element

```
rcu_read_lock();  
p = search(key);  
if (p != NULL) {  
    spin_lock(&p->mutex);  
    if (p->deleted) {  
        spin_unlock(&p->mutex);  
        p = NULL;  
    }  
}  
rcu_read_unlock();  
return (p);
```

Ordered Update with Ordered Read

- Expanding array

```
/* update */
new_array = kmalloc(new_size * sizeof(*newarray));
copy_and_init(new_array, array);
smp_wmb();
array = new_array;
smp_wmb();
size = new_size;

/* read */
if (i >= size)
    return -ENOENT;
smp_rmb();
p = array;
smp_read_barrier_depends();
return p[i];
```

- Usually better to impose level of indirection...

Global Version Number

- In Linux, combine `seqlock_t` with RCU
- For example, in `dcache` lookup:

```
do {  
    seq = read_seqbegin(&rename_lock);  
    dentry = __d_lookup(parent, name);  
    if (dentry)  
        break;  
} while (read_seqretry(&rename_lock, seq));
```

- RCU protects against cache prune and “rm”
- `seqlock_t` protects against “mv”
- Could also place sequence number in `dentry` to allow “mass invalidate” of `dentries`

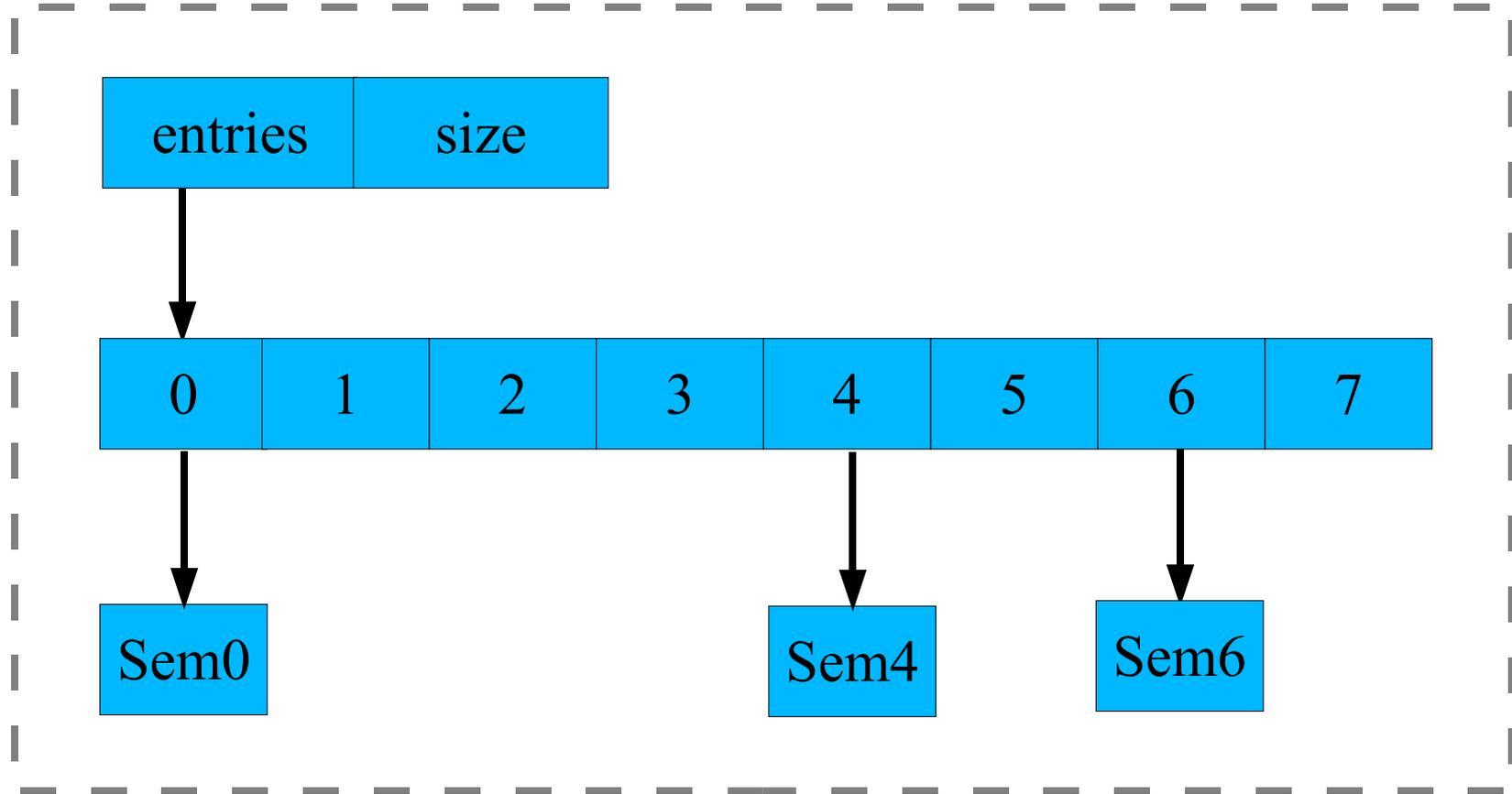
RCU Transformational Patterns

- Substitute Copy for Original (2)
- Impose Level of Indirection (~1)
- Mark Obsolete Objects (2)
- Ordered Update With Ordered Read (3)
- Global Version Number (2)
- Stall Updates (~1)

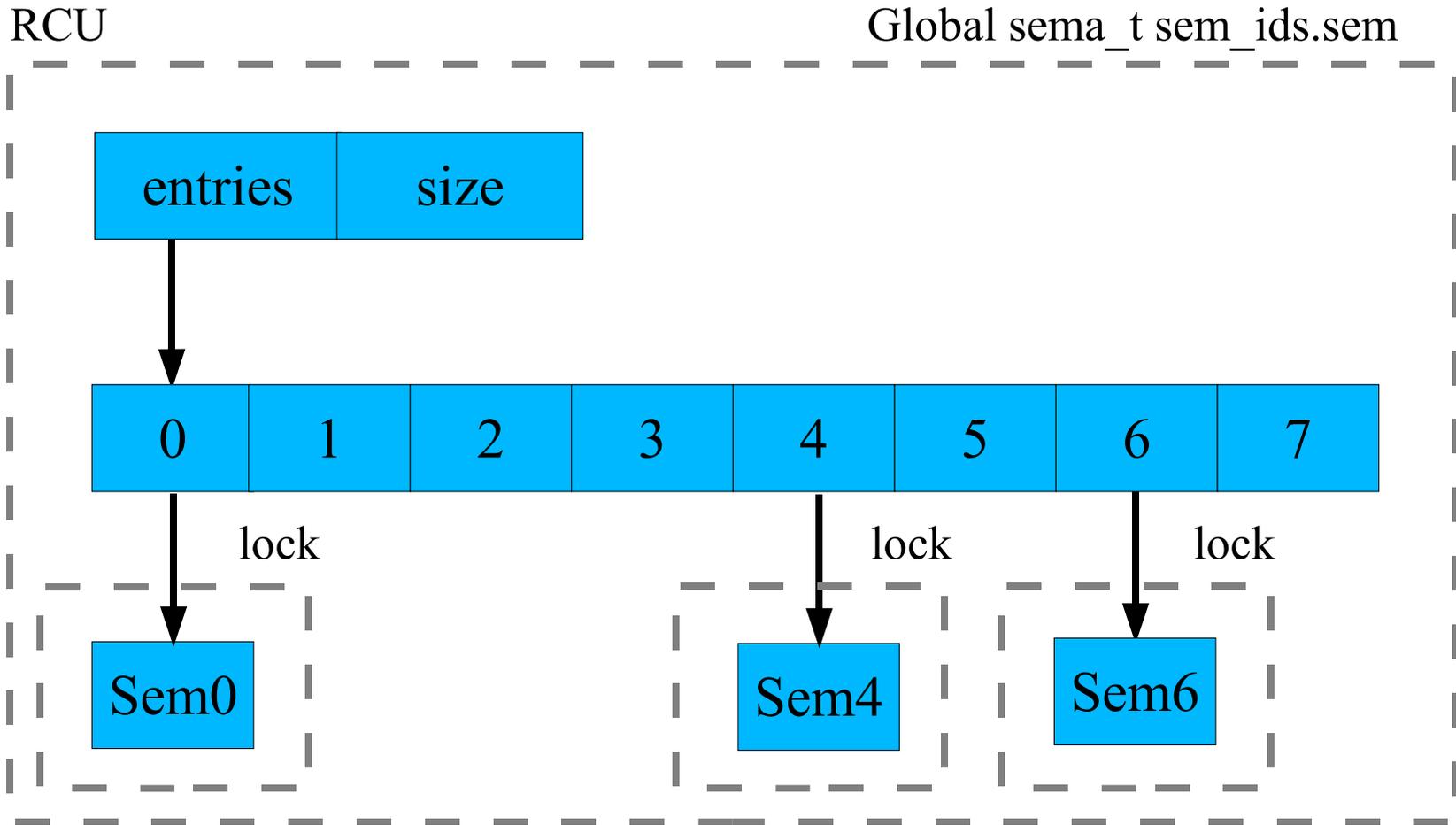
Putting It All Together

2.4 System V Semaphore Locking

Global sema_t sem_ids.sem
Global spinlock_t sem_ids.ary

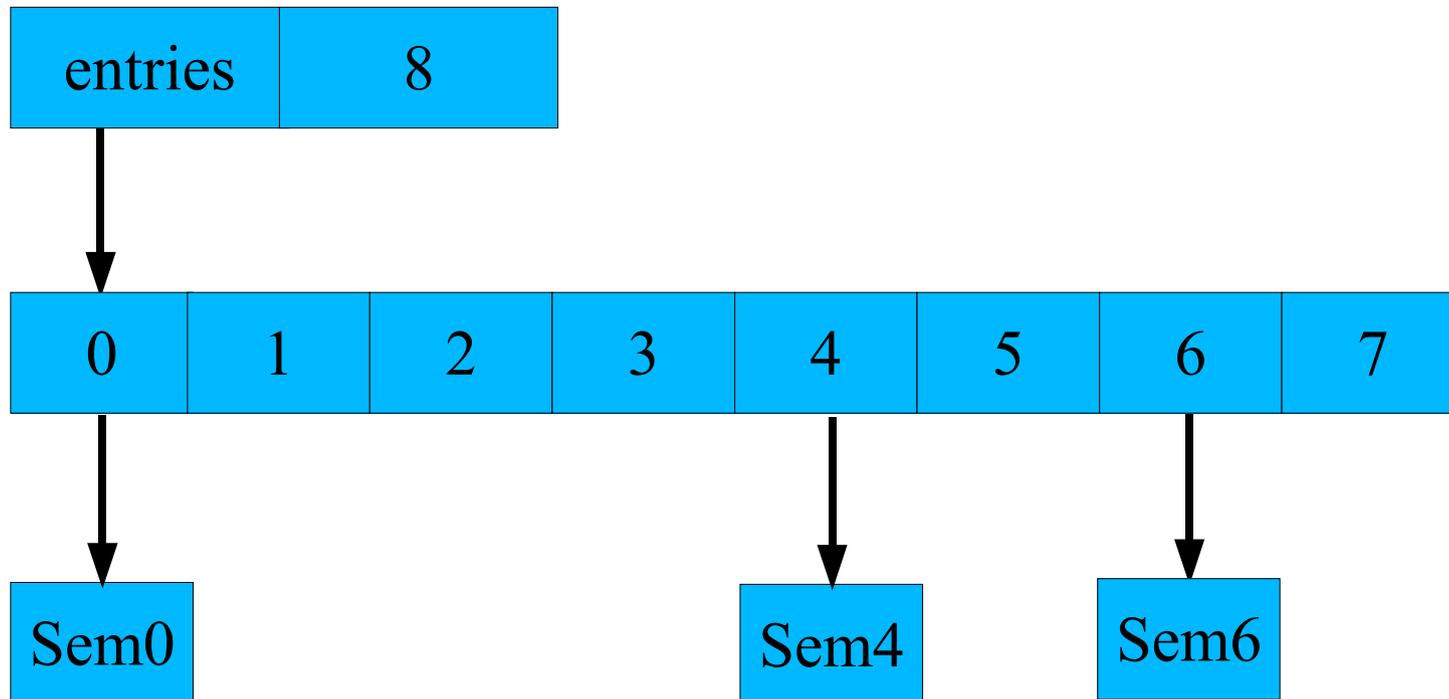


2.6 System V Semaphore Locking

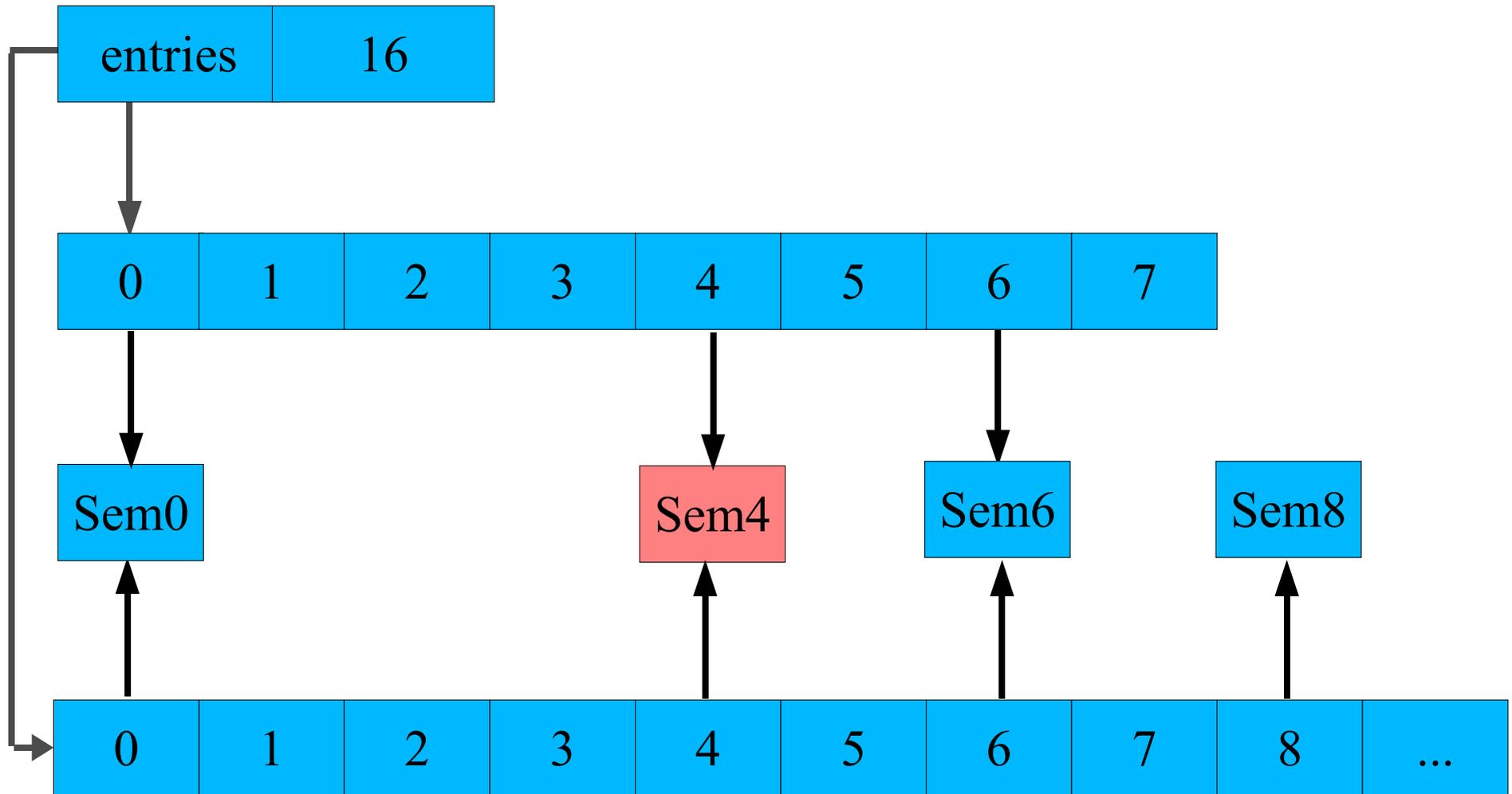


Each semaphore has a “deleted” flag to force search failure

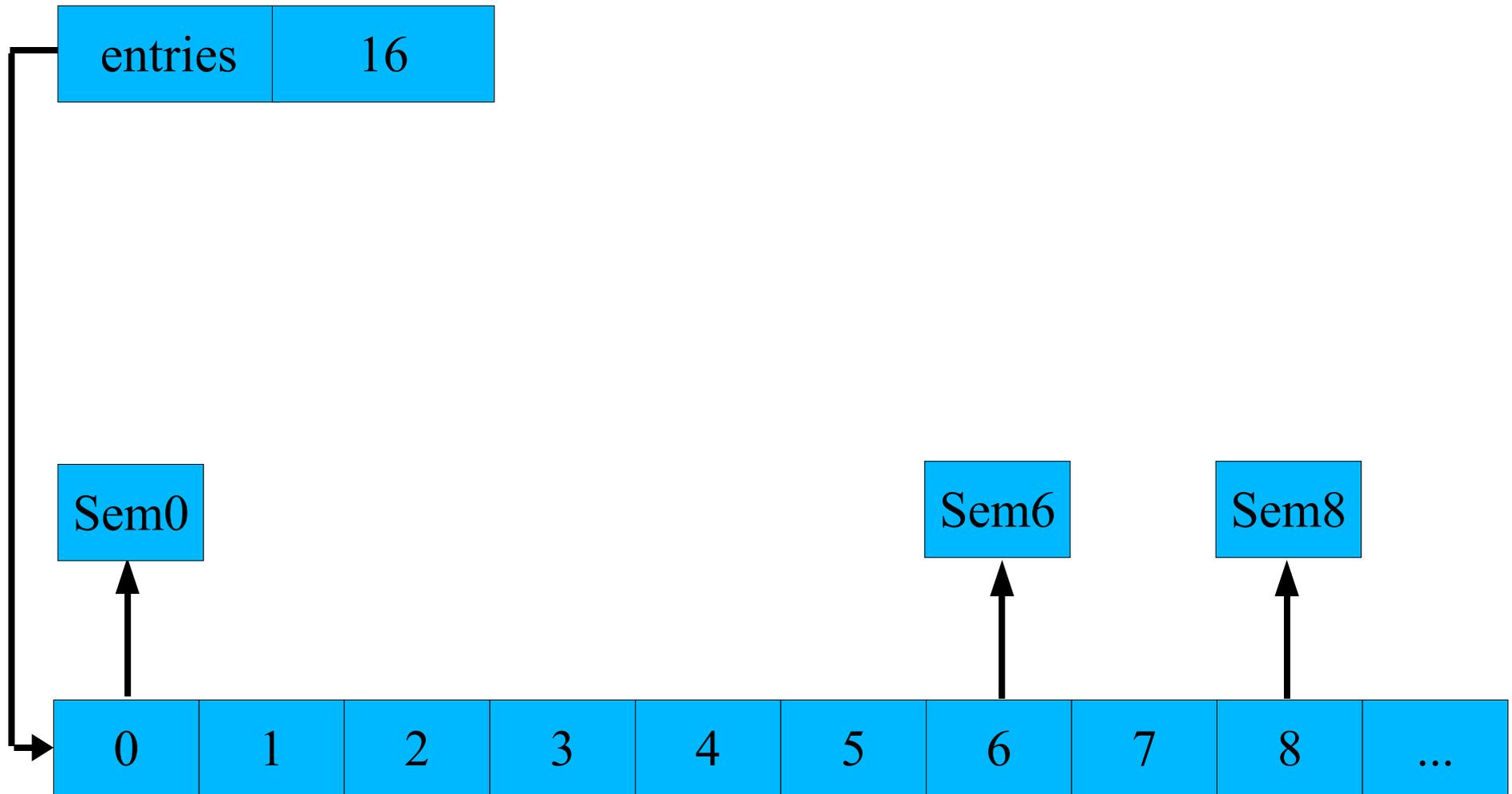
2.6 SysV Sema Animation (1)



2.6 SysV Sema Animation (2)



2.6 SysV Sema Animation (3)



Searching for Semaphore

```
rcu_read_lock();
if(lid >= ids->size) {
    rcu_read_unlock();
    return NULL;
}
smp_rmb(); /* prevent indexing old array with new size */
entries = ids->entries;
read_barrier_depends(); /*prevent seeing new array unitialized */
out = entries[lid].p;
if(out == NULL) {
    rcu_read_unlock();
    return NULL;
}
spin_lock(&out->lock);
if (out->deleted) {
    spin_unlock(&out->lock);
    rcu_read_unlock();
    return NULL;
}
return out;
```

Expanding Semaphore Array

```
old = ids->entries;
i = ids->size;

smp_wmb();    /* prevent seeing new array uninitialized. */
ids->entries = new;
smp_wmb();    /* prevent indexing into old array based on new size. */
ids->size = newsize;

ipc_rcu_free(old, sizeof(struct ipc_id)*i);
return ids->size;
```

RCU Sem Micro-Benchmark

Kernel	Run 1	Run 2	Avg
2.5.42-mm2	515.1	515.4	515.3
2.5.42-mm2+ipc-rcu	46.7	46.7	46.7

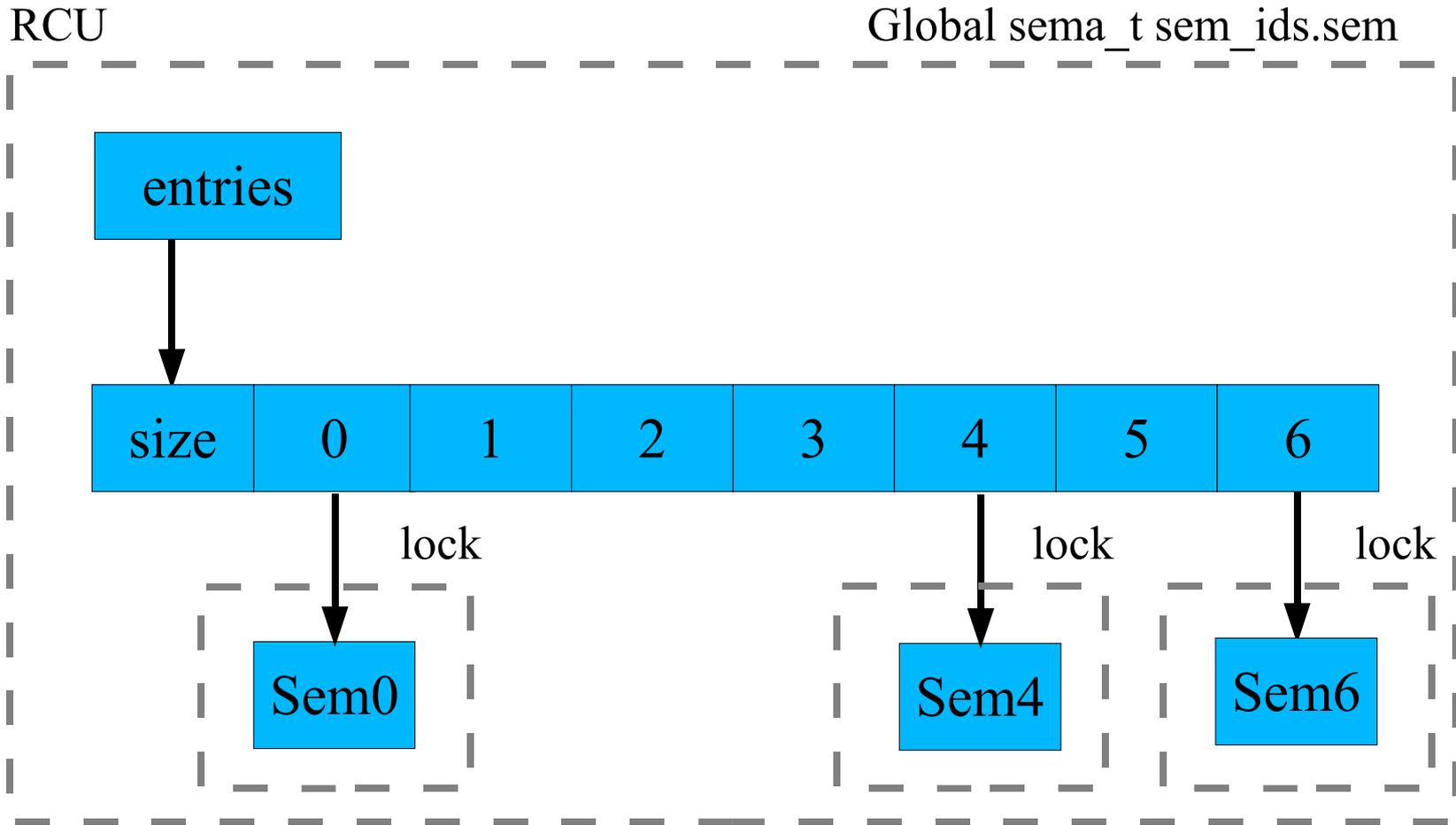
Numbers are test duration, smaller is better.

RCU Sem DBT1 Performance

Kernel	Average	Standard Deviation
2.5.42-mm2	85.0	7.5
2.5.42-mm2+ipc-rcu	89.8	1.0

Numbers are transaction rate, larger is better.

Proposed Locking



Each semaphore has a “deleted” flag to force search failure

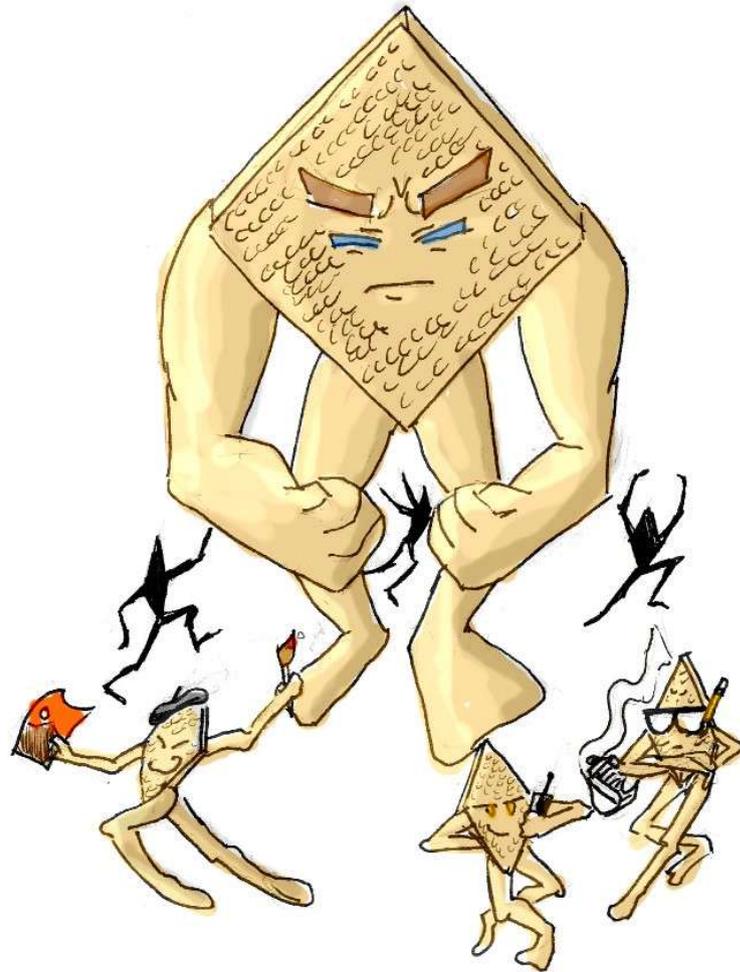
The Road Ahead

Uniprocessor Über Alles



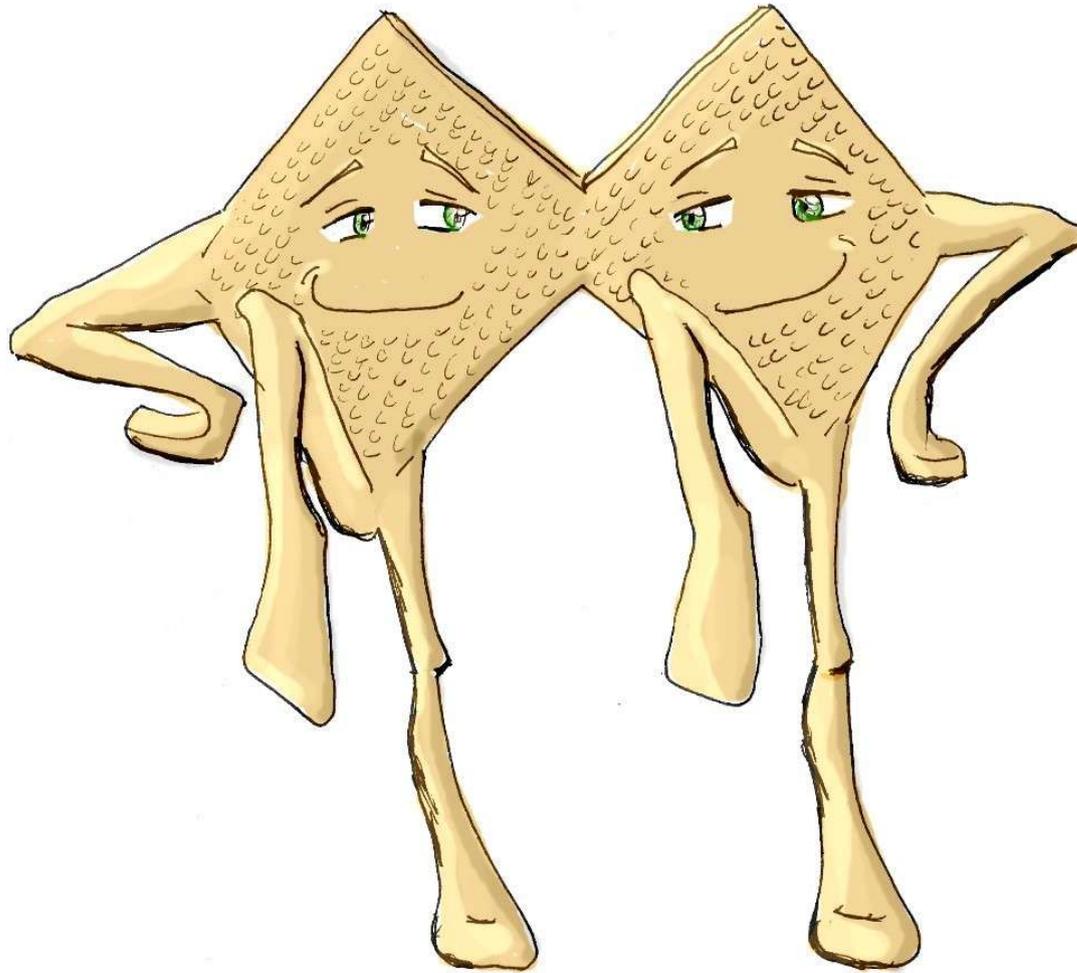
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Uniprocessor With Friends



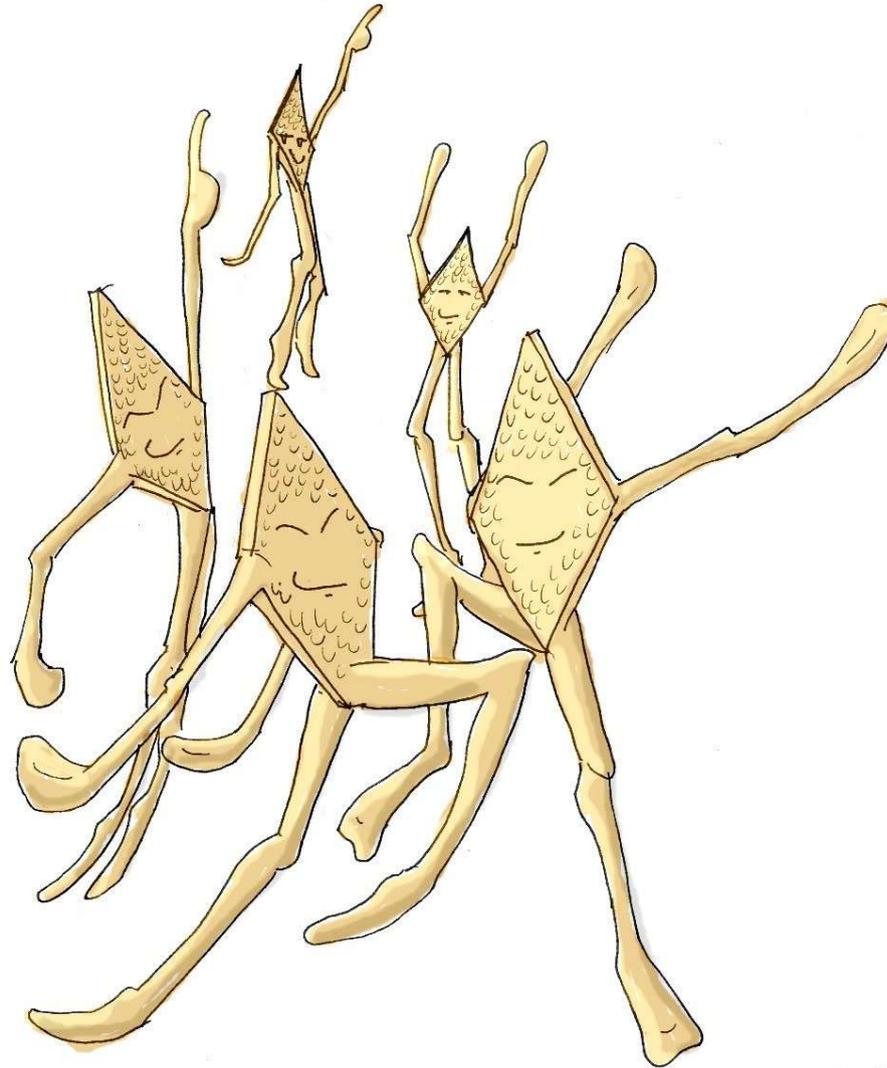
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Multithreaded Mania



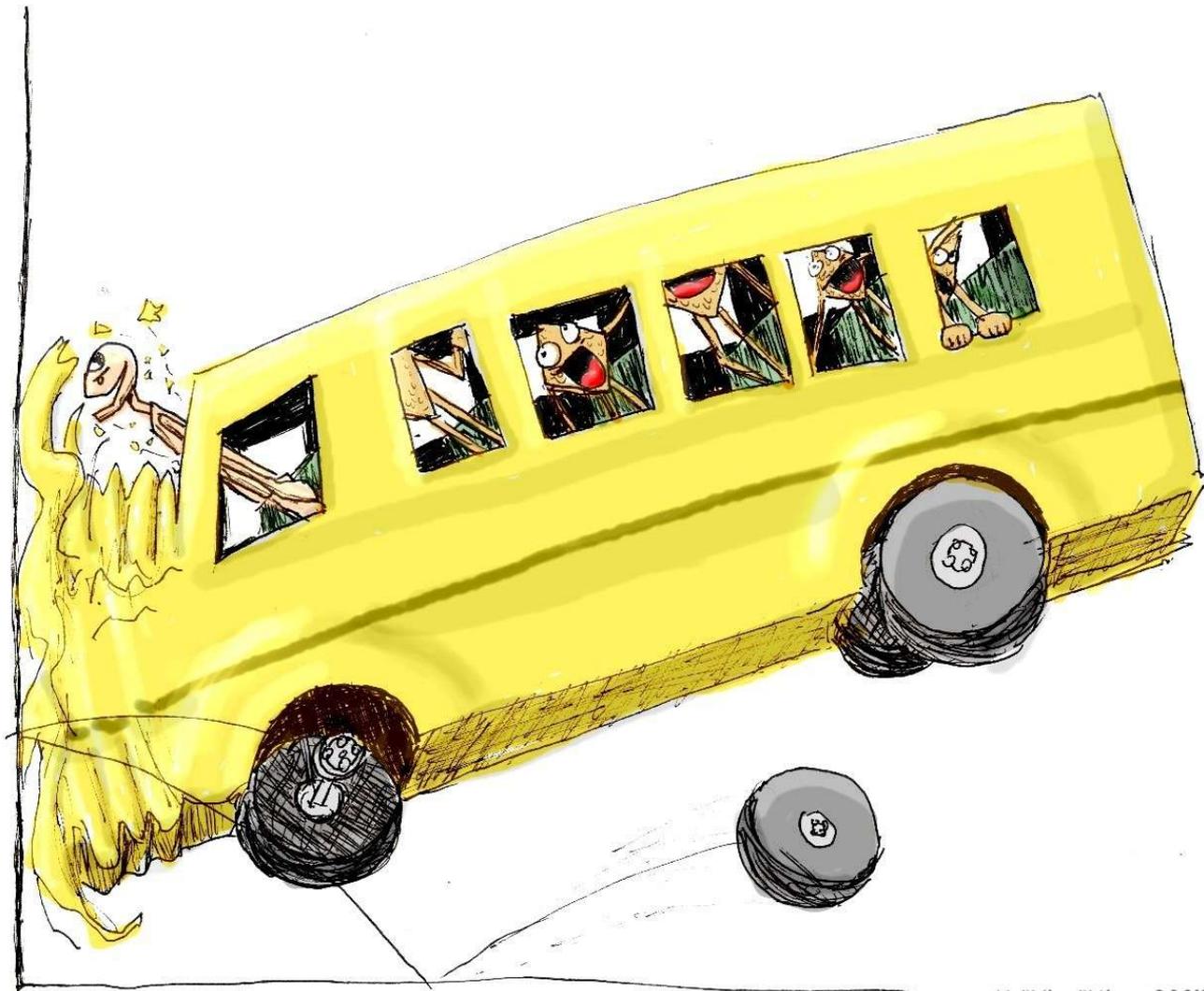
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More of the Same



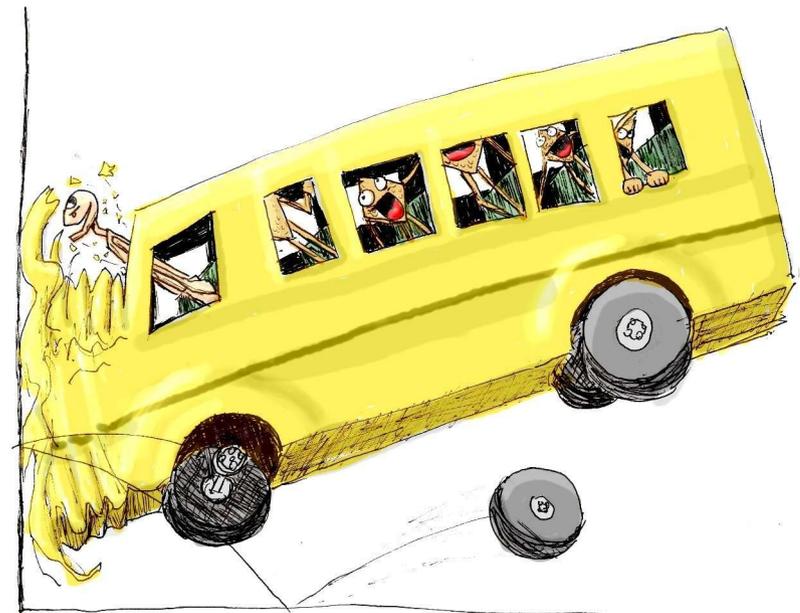
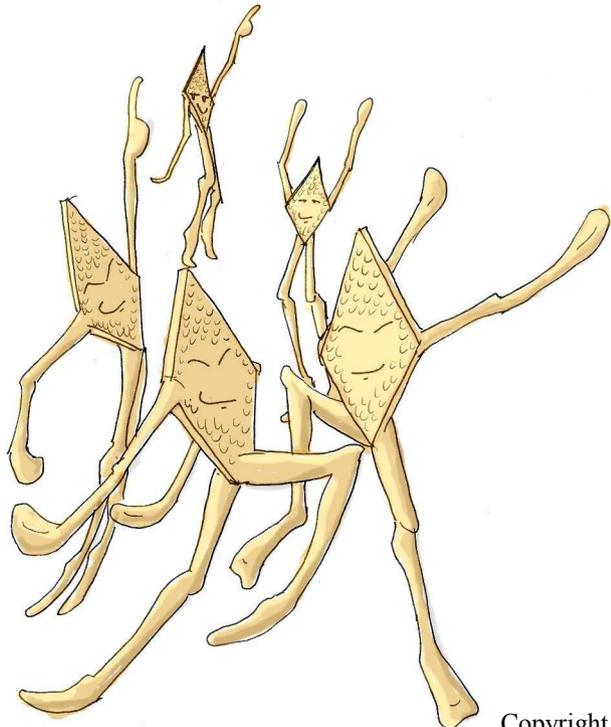
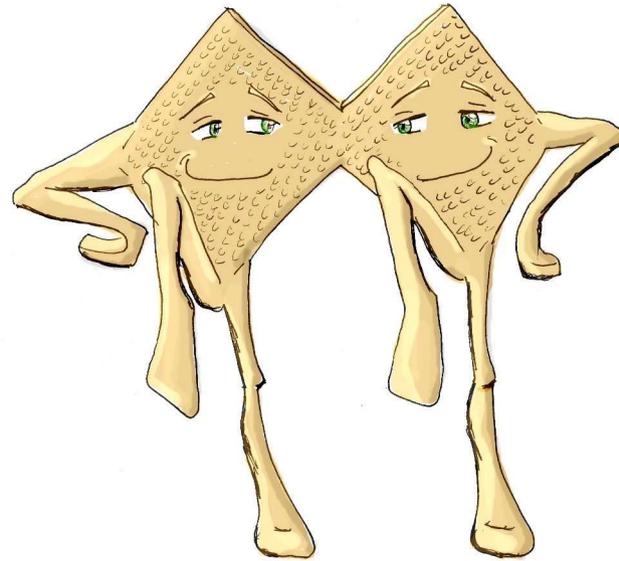
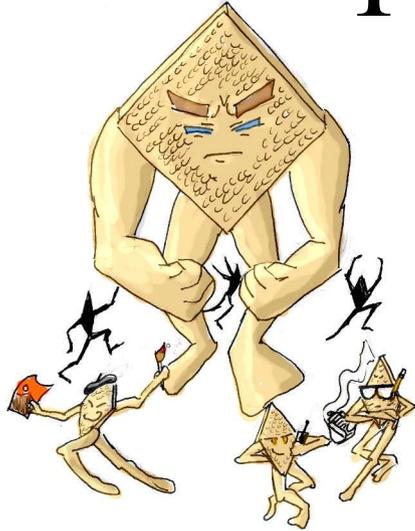
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Crash Dummies Slamming into the Memory Wall



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Your Predictions?

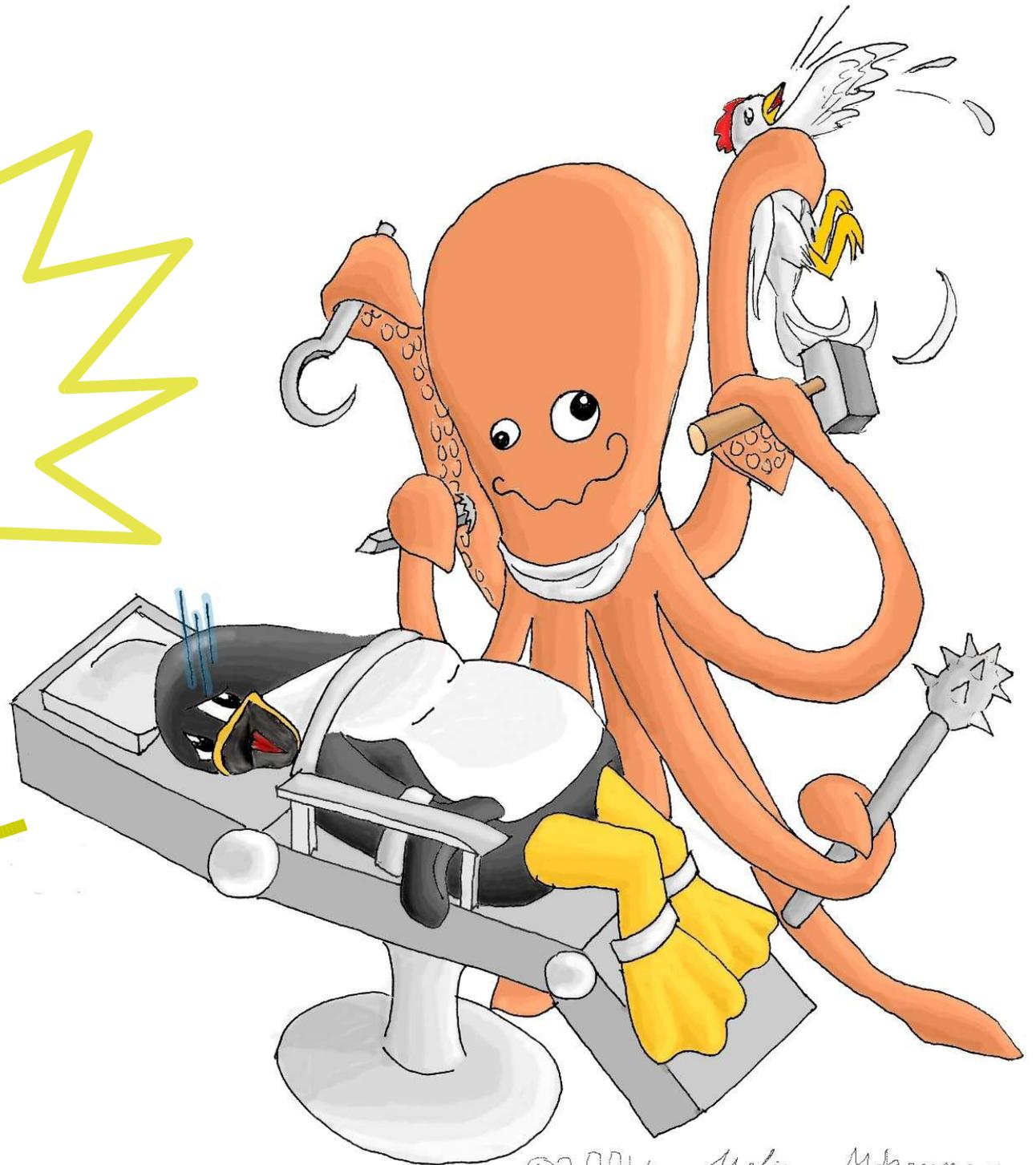


My Guess...

Somewhere between Multithreaded Mania and More of the Same, with both hardware threading and multicore dies.

Summary and Conclusions

*Use
the right tool
for the job!!!*



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BACKUP